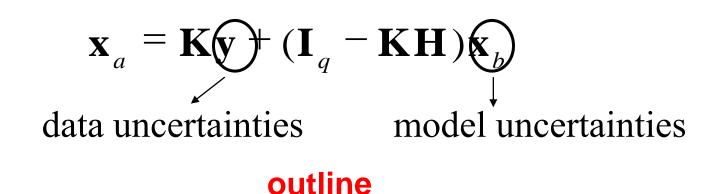
# Ensemble Data Assimilation: Perturbing the background state to represent model uncertainties

## Carla Cardinali Nedjeljka Zagar , Gabor Radnoti, Roberto Buizza



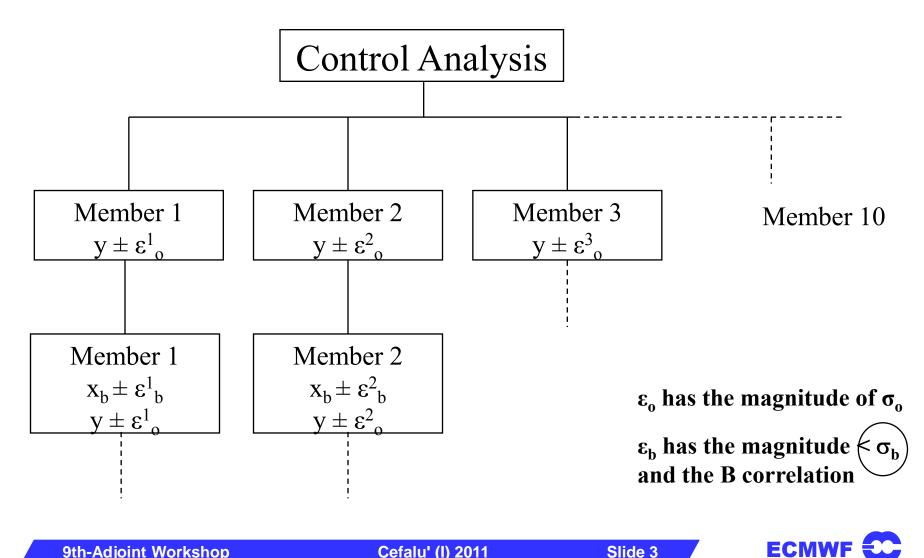
## **Ensemble Data Assimilation:** Perturbing the background state to represent model uncertainties



- EDA perturbing y and x<sub>b</sub>
- Comparisons with EDA with different model error representation and EDA where only data error is represented
- Diagnostics on the B derived from all different EDA
- EDAs performance in the EPS
- Conclusion



### **Ensemble Data Assimilation** perturbing the background state to represent model uncertainties



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# Ensemble Data Assimilation Experiment set-up

Realization:10 member Resolution: T399T159L91 Period: 20081005-20081115

In Model error representation:

Systematic kinetic energy loss numerical integrations and parametrization

-BS Spectral Stochastic Kinetic Energy Backscatter scheme (Berner et Infal. 2009)

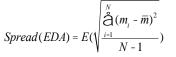
-ST Stochastic representation of model error associated to parametrized physical processes tendencies (Buizza et al. 1999) - $X_b$  Perturbed background with gaussian random correlated perturbation  $\varepsilon_b = 0.5 \sigma_b$ 

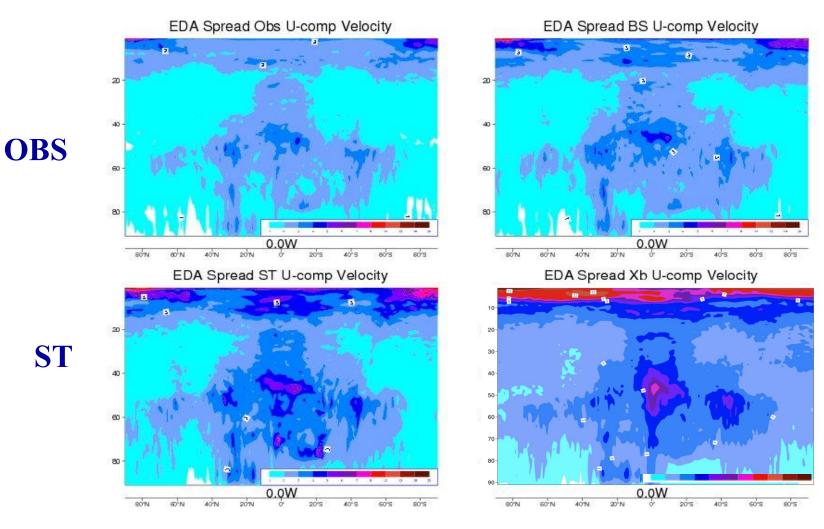
-OBS (Infl) Perturbed observation with gaussian random perturbation and inflated background error variances



# **Ensemble Data Assimilation**

Zonal averaged cross section u-comp ensemble spread





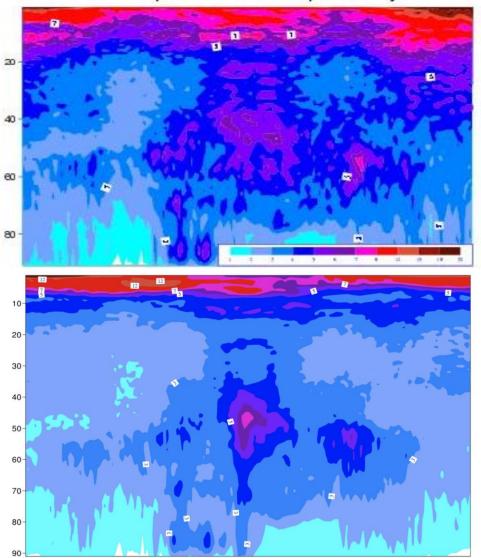
BS

 $\mathbf{X}_{\mathsf{b}}$ 



# **Ensemble Data Assimilation: X**<sub>b</sub>

EDA Spread Xb U-comp Velocity



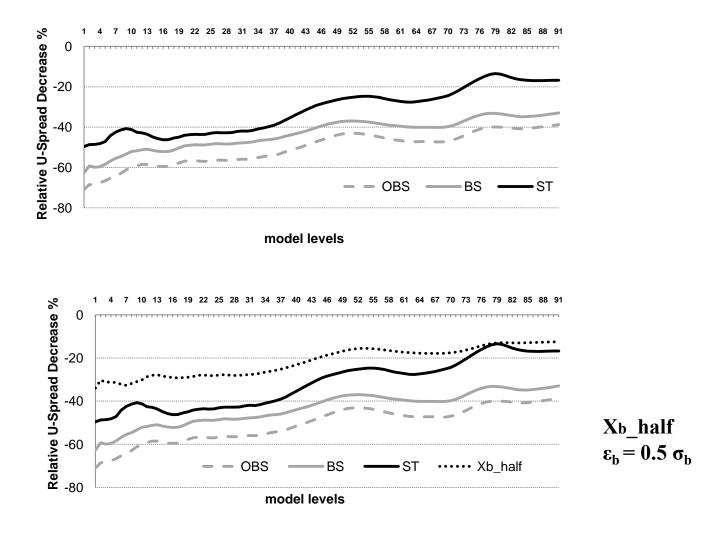
$$\varepsilon_b = \sigma_b$$

 $\varepsilon_{\rm b} = 0.5 \sigma_{\rm b}$ 



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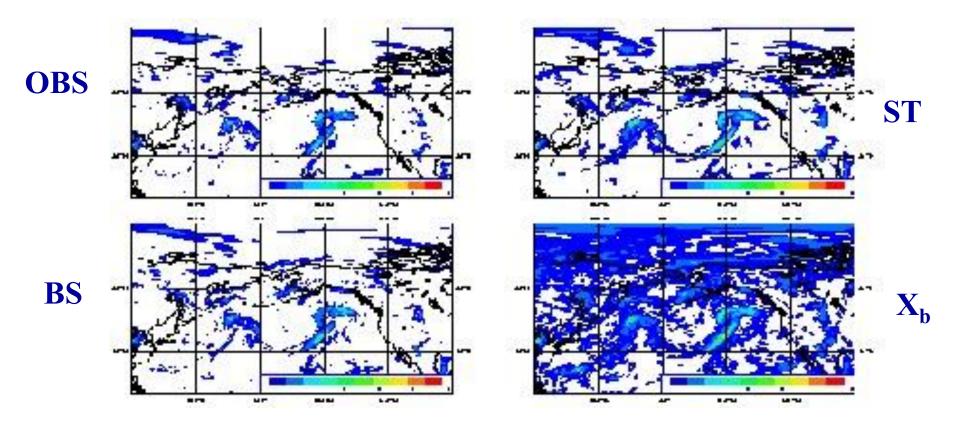
# **Ensemble Data Assimilation: u-spread**





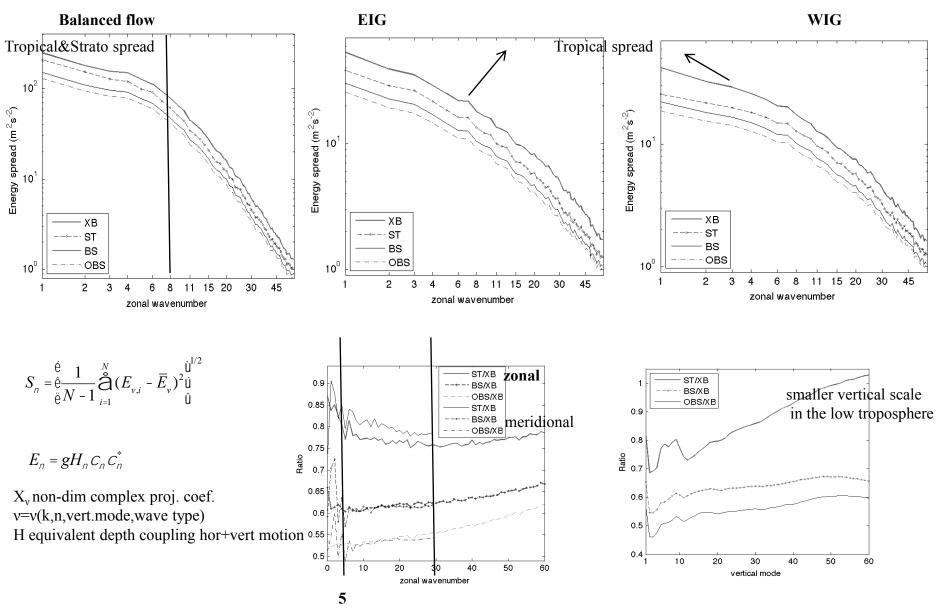
#### **Ensemble Data Assimilation: Baroclinic development**

6-h fc valid on 21 October 12 UTC850 hPa vorticity spread



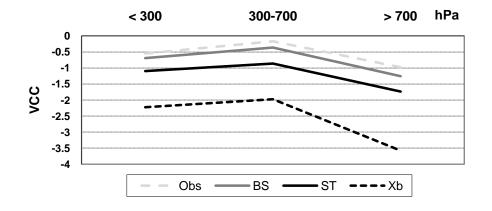


# EDA: Energetic diagnosis of the ensemble spread



ECMWF

#### **Observation Space Diagnostic B computed from EDAs** Desroziers et al. 2005 $\mathbf{HBH}^{\mathrm{T}} = \mathbf{E}(\mathbf{d}_{\mathbf{h}}^{a}(\mathbf{d}_{\mathbf{h}}^{o})^{\mathrm{T}})$ $\mathbf{d_b}^a = \mathbf{H}\mathbf{x_a} - \mathbf{H}\mathbf{x_b}$ $\mathbf{d_b}^o = \mathbf{y} - \mathbf{H}\mathbf{x_b}$ VarianceConsinstencyCheck= $HB H^{T}_{estimated} - HBH^{T}_{assigned}$ 2 0 -2 AMSU-A -4 VCC -6 -8 -10 Obs • BS • ST -**- -** XF -12 5 13 12 11 10 q 8 7 6 Channel



Wind Observations

Slide 10

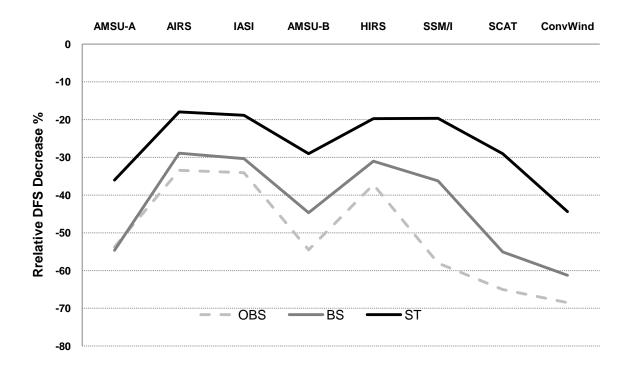


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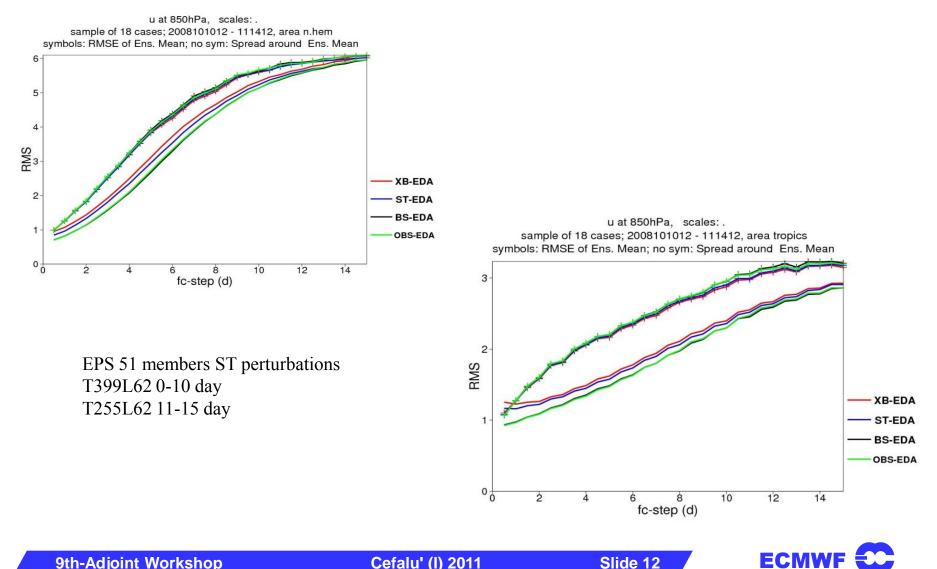
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#### **Observation Space Diagnostic Observation Influence** Cardinali et al. 2004

$$\frac{\partial \mathbf{H} \mathbf{x}_{a}}{\partial \mathbf{v}} = \mathbf{K}^{T} \mathbf{H}^{T} \qquad \mathbf{K} = (\mathbf{B}^{-1} + \mathbf{H}^{T} \mathbf{R}^{-1} \mathbf{H})^{-1} \mathbf{H}^{T} \mathbf{R}^{-1}$$

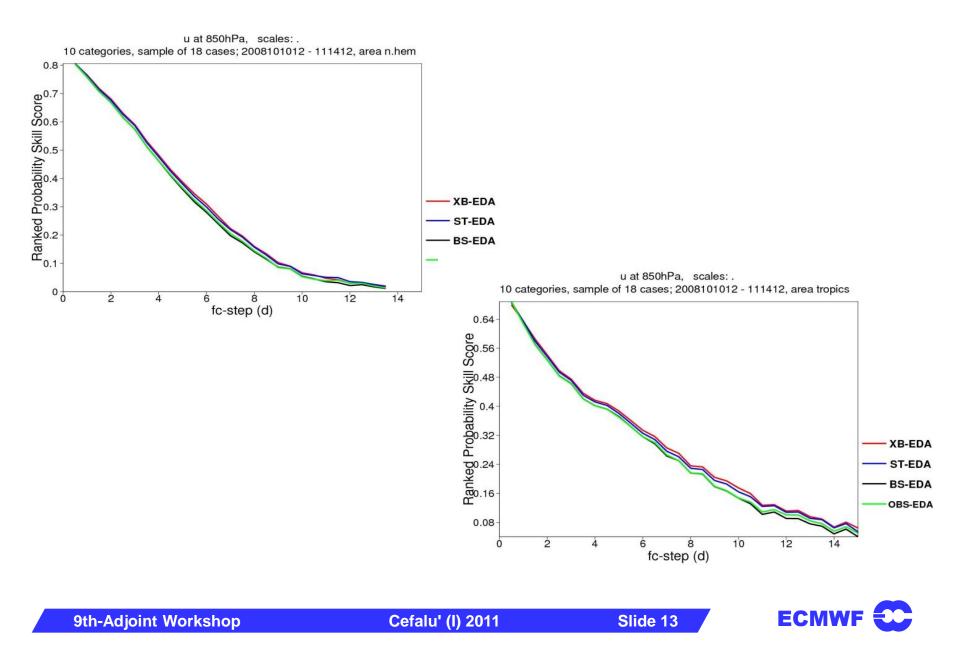


#### **EDAs used to generate initial perturbations for the EPS**



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#### **EDAs used to generate initial perturbations for the EPS**



#### **Perturbing the background state versus Others:**

Perturbing the background state add more spread in the tropics and extra-tropics

Increase of spread in the stratosphere

Increase of spread in less observed areas and dynamically active areas

When the B is computed from the EDAs largest OI is achieved

Results from EPS show larger spread in the Tropics and in the Extra-Tropics

Very easy to maintain does not require tuning from one model-cycle to an other

> To determine the correct perturbation amplitude the following comparisons are planned:

OBS ensemble spread versus innovation vector spread of the Control analysis

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