

# GEOS-S2S Version 2: The GMAO High Resolution Coupled Model and Assimilation System for Seasonal Prediction

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## Key Points:

- Atmosphere-Ocean Modeling
- Atmosphere-Ocean Data Assimilation
- Seasonal and Subseasonal Prediction

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**Abstract**

TEXT

**1 Introduction**

The Global Modeling and Assimilation Office (GMAO) has recently released a new version of the Goddard Earth Observing System (GEOS) Sub-seasonal to Seasonal prediction (S2S) system, GEOS-S2S Version 2. The S2S system includes an Atmosphere-Ocean General Circulation Model (AOGCM) an ocean data assimilation system (ODAS), and a methodology for weakly coupled Atmosphere-Ocean Coupled Data Assimilation (AO-CDAS). This new version of GEOS-S2S represents a substantial improvement in performance and system infrastructure relative to the previous version, retroactively named GEOS-S2S Version 1, that was described in *Borovikov et al.* [2017].

The GEOS system has a long history of being successfully employed in seasonal prediction efforts and contributing to multi-system ensemble projects. For example, the GEOS system has been a participating model in the North American Multi-model Ensemble [*Kirtman et al.*, 2014] since that project's inception in 2011. The GEOS forecasts also routinely contribute to various other national and international multi-model ensembles including the multi-model forecast products at the International Research Institute for Climate and Society (IRI) of Columbia University and those of the APEC Climate Center, Korea, thus enabling rigorous evaluations of the forecast skill and model biases and orienting the performance of the GEOS-S2S system relative to other state-of-the art systems. The new system described here (GEOS-S2S Version 2) builds upon the already established experimental seasonal prediction system at the GMAO [*Borovikov et al.*, 2017], and further expands it to produce near-real-time weekly initialized forecasts at the subseasonal timescale, also facilitating GMAO's participation in the NOAA's experimental subseasonal multi-model ensemble project (<http://cola.gmu.edu/kpegon/subx/index.html>).

In this paper, we describe the GEOS-S2S Version 2 system, emphasizing the improvements over Version 1, and assess the performance of climate, forecasts and data assimilation. Section 2 presents a description of the model and data assimilation system, section 3 describes the experiments performed with the new system that will be analyzed here, results of the experiments are presented and compared with results from the old system and observational estimates in sections 4, 5 and 6 and the study is summarized in section 7.

**2 Description of Coupled Model and Data Assimilation System**

The GEOS AOGCM and Data Assimilation System (AODAS) are developed to simulate the earth system on a wide range (synoptic to decadal) of time scales. The main components of the GEOS-S2S are the GEOS AOGCM, which in-turn consists of the GEOS atmospheric general circulation model [*Molod et al.*, 2015; *Rienecker et al.*, 2008], the catchment land surface model [*Koster et al.*, 2000], and the Goddard Chemistry Aerosol Radiation and Transport (GOCART) aerosol model **REFS**. The ocean general circulation model is the Modular Ocean Model-5 (MOM5) developed by the Geophysical Fluid Dynamics Laboratory [*Griffies et al.*, 2005; *Griffies*, 2012], coupled to the Community Ice Code-4 (CICE4) sea ice model developed at Los Alamos National Lab (LANL, [*Hunke and Lipscomb*, 2008]). The atmospheric data assimilation component is the pre-existing "Forward Processing for Instrument Teams" near-real time assimilation ([https://gmao.gsfc.nasa.gov/products/GEOS-5\\_FP-IT\\_details.php](https://gmao.gsfc.nasa.gov/products/GEOS-5_FP-IT_details.php)), and the ocean data assimilation follows the Local Ensemble Transform Kalman Filter (LETKF) [*Penny et al.*, 2013]. All components are coupled together using the Earth System Modeling Framework (ESMF, [*Hill et al.*, 2004]) and the MAPL interface layer [*Suarez et al.*, 2007]. Various operational centers are developing AO-CDAS systems [*Dee et al.*, 2014; *Brassington et al.*, 2015], in which different components (e.g., atmosphere and ocean) of the earth system are analyzed separately [*Laloyaux et al.*, 2016; *Lea et al.*, 2015]

70 or simultaneously [Sluka *et al.*, 2016; Wada and Kunii, 2017]. The GEOS-S2S AO-CDAS  
 71 relies on an pre-computed atmospheric analysis, performing an analysis of the ocean state  
 72 only. Each of the components of the GEOS S2S Version 2 system will be described here in  
 73 varying amounts of detail.

## 74 **2.1 Coupled Atmosphere-Ocean General Circulation Model**

### 75 **2.1.1 Atmospheric, Land and Aerosol Models**

76 The version of the GEOS AGCM that is used as part of the GEOS Seasonal to Sub-  
 77 seasonal (S2S) prediction system Version 2 contains algorithms that describe atmospheric  
 78 transport and dynamics, atmospheric physical processes, a land model and an interactive  
 79 aerosol model. The algorithm for large-scale transport and dynamics in the current GEOS  
 80 AGCM is an adaptation of the flux-form semi-Lagrangian (FFSL) finite-volume (FV) dy-  
 81 namics of Lin [2004], adapted for a cubed sphere horizontal discretization [Putman and Lin,  
 82 2007]. A comprehensive description of baseline versions of the physical parameterizations is  
 83 found in Rienecker *et al.* [2008], and the updates to a recent version of the AGCM are found  
 84 in Molod *et al.* [2015]. GEOS AGCM physical parameterizations include schemes for con-  
 85 vection, large scale precipitation and cloud cover, longwave and shortwave radiation, turbu-  
 86 lence, and gravity wave drag.

87 Convection is parameterized using the Relaxed Arakawa-Schubert scheme [Moorthi  
 88 and Suarez, 1992], which contains an updraft-only cloud model and a quasi-equilibrium clo-  
 89 sure. The frequency and intensity of deep convection is governed by a stochastic Tokioka-  
 90 type trigger function [Tokioka *et al.*, 1988] as suggested by Bacmeister and Stephens [2011].  
 91 Prognostic cloud cover and cloud water and ice are determined by the two moment param-  
 92 eterization of Barahona *et al.* [2014], which predicts both the amount and number concen-  
 93 tration of cloud water and cloud ice. Processes include cloud particle nucleation, large scale  
 94 condensation, evaporation, autoconversion and accretion of cloud water and ice, sedimen-  
 95 tation of cloud ice, and re-evaporation of falling precipitation. The probability distribution  
 96 function (PDF) for total water that governs the condensation and evaporation processes is  
 97 described by Molod [2012].

98 Longwave radiative processes are described by Chou and Suarez [1994], and include  
 99 absorption due to cloud water, water vapor, aerosols, carbon dioxide (CO<sub>2</sub>), ozone (O<sub>3</sub>),  
 100 nitrous oxide (N<sub>2</sub>O), methane (CH<sub>4</sub>), chlorofluorocarbons CFC-11 and CFC-12, and hy-  
 101 drochlorofluorocarbon HCFC-22. Shortwave radiative transfer is from Chou [1990, 1992],  
 102 and includes absorption by water vapor, cloud water, O<sub>3</sub>, CO<sub>2</sub>, molecular oxygen (O<sub>2</sub>), and  
 103 aerosols, and scattering by cloud water and aerosols.

104 The turbulence parameterization is based on the Lock scheme [Lock *et al.*, 2000] com-  
 105 bined with the Richardson-number based algorithm of Louis and Geleyn [1982]. The former  
 106 includes a representation of non-local mixing driven by both surface fluxes and cloud-top  
 107 processes in unstable layers, either coupled to or decoupled from the surface. It was extended  
 108 in GEOS to include moist heating and entrainment in the unstable surface parcel calculations  
 109 which determine the depth of unstable layers. The latter is a first-order local scheme, and its  
 110 effect is mostly felt just above the surface layer and in regions of shear-generated turbulence.  
 111 The turbulent length scale that governs its behavior is a function of the planetary boundary  
 112 layer height at the previous time step [Molod *et al.*, 2015], which is diagnosed based on the  
 113 profile of eddy diffusivity over the ocean and on a bulk Richardson number threshold over  
 114 land [McGrath-Spangler and Molod, 2014]. The Monin-Obukhov surface layer parameter-  
 115 ization is described by Helfand and Schubert [1995] and includes the effects of a viscous  
 116 sublayer for heat and moisture transport over all surfaces except land. Ocean surface rough-  
 117 ness is determined by a blend of the algorithms of Large and Pond [1981] and Kondo [1975],  
 118 modified in the midrange wind regime according to Garfinkel *et al.* [2011] and in the high  
 119 wind regime according to Molod *et al.* [2013].

120 The gravity wave drag parameterization computes momentum and heat deposition due  
 121 to orographic [McFarlane, 1987] and nonorographic [Garcia and Boville, 1994] waves. The  
 122 background drag profile that generates an internal quasi-biennial oscillation (QBO) is de-  
 123 scribed by Molod *et al.* [2015]. They demonstrate that downward propagation of the zonal  
 124 wind anomalies is realistic, but phase speeds are slower and amplitudes are larger than those  
 125 observed.

126 The Land Surface Model from Koster *et al.* [2000] is a catchment-based scheme that  
 127 treats subgrid scale heterogeneity in surface moisture statistically. Glacial thermodynamic  
 128 process are parameterized using an adaptation of the Stieglitz *et al.* [2001] snow model to  
 129 glacial ice [Cullather *et al.*, 2014], and the catchment and glacier models are each coupled to  
 130 the multi-layer snow model developed by Stieglitz *et al.* [2001]. Sea ice albedos in the north-  
 131 ern hemisphere are from the monthly mean observations of Duynkerke and de Roode (2001).  
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### 134 2.1.2 Ocean and Sea Ice Models

135 The ocean component of the GEOS AOGCM is the Modular Ocean Model version  
 136 5 (MOM5) developed at Geophysical Fluid Dynamics Laboratory, [Griffies *et al.*, 2005;  
 137 Griffies, 2012]. It is a hydrostatic primitive equations model with a staggered Arakawa B-  
 138 grid, [Mesinger and Arakawa, 1976] and vertical coordinate based on depth. A tripolar grid  
 139 is used to resolve the Arctic Ocean without polar filtering, [Murray, 1996]. The model uses  
 140 a three level time stepping scheme. The ocean surface boundary is computed as an explicit  
 141 free surface with real fresh water forcing. The topography is represented as a partial bot-  
 142 tom step to better represent topographically influenced advective and wave processes. Ver-  
 143 tical mixing follows non-local K-profile parametrization of Large *et al.* [1994] and includes  
 144 parametrization of tidal mixing on continental shelves. Horizontal mixing uses the isoneutral  
 145 method developed by Gent and McWilliams [1990]. The horizontal viscosity uses anisotropic  
 146 scheme of Large *et al.* [2001] for better representation of equatorial currents. The exchange  
 147 with marginal seas is parametrized under coarse resolution as discussed in Griffies [2012].

148 The sea ice component of the GEOS AOGCM is the CICE 4.1 developed by the Los  
 149 Alamos National Laboratory, [Hunke and Lipscomb, 2008]. The model includes several in-  
 150 teracting components: a thermodynamic model that computes local growth rates of snow and  
 151 ice due to vertical conductive, radiative and turbulent fluxes, along with snowfall; a model of  
 152 ice dynamics, which predicts the velocity field of the ice pack based on a model of the mate-  
 153 rial strength of the ice; a transport model that describes advection of the areal concentration,  
 154 ice volumes and other state variables; and a ridging parameterization that transfers ice among  
 155 thickness categories based on energetic balances and rates of strain.

156 The ocean and atmosphere exchange fluxes of momentum, heat and fresh water through  
 157 a "skin layer" interface which includes a parameterization of the diurnal cycle [Price *et al.*,  
 158 1978].

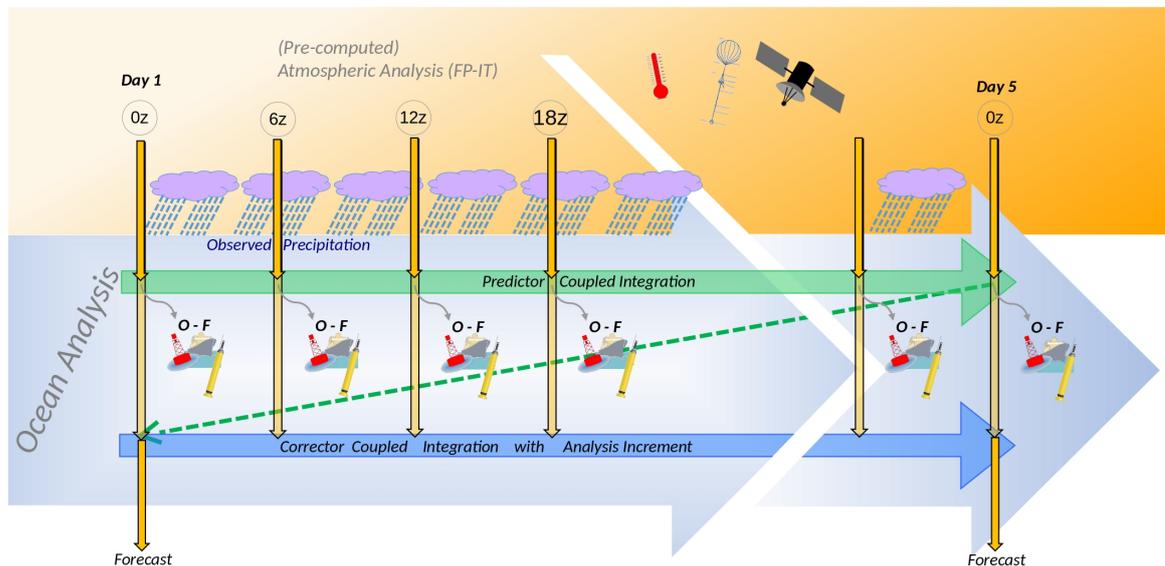
## 159 2.2 Coupled Atmosphere and Ocean Data Assimilation

### 160 2.2.1 Data Assimilation Method

161 Similar to Version 1, the GEOS S2S Version 2 AO-CDAS is a weakly coupled atmosphere-  
 162 ocean data assimilation system, as depicted in Figure 1. During all stages of the data assim-  
 163 ilation, the coupled AOGCM is performing the simulations, and the AO-CDAS includes an  
 164 ocean predictor sequence (the green line across the top of the figure), during which the atmo-  
 165 spheric state is "replayed" using an "intermittent replay" [??] to GMAO's "Forward Process-  
 166 ing for Instrument Teams" (FPIT) atmospheric reanalysis. The land is driven using observed  
 167 CMAP precipitation [?], [Xie and Arkin, 1997]. After a 5-day segment, the ocean analysis in-

168 crements are computed (see below for a description) and the AO-CDAS returns to the begin-  
 169 ning of the 5-day segment to perform the corrector segment (blue arrow across the bottom)  
 170 using the Incremental Analysis Update (IAU) method of *Bloom et al.* [1996].

171 Throughout the predictor and corrector steps (depicted in Figure 1), as the coupled  
 172 atmosphere-ocean model is integrated in time, the sea surface temperature (SST) is strongly  
 173 relaxed (with a 1-day relaxation time-scale) to the MERRA-2 [*Gelaro et al., 2017*] SST (also  
 174 used in FPIT) so that the simulated atmosphere in this coupled system is as consistent as possible  
 175 with the FPIT atmospheric reanalysis. It should be noted that the present GEOS S2S-2  
 176 system has no relaxation to salinity. As the predictor segment proceeds, every 6-hours the  
 177 departure of the model trajectory (i.e., background field) from observations is gathered, via  
 178 the so-called ocean *observers*. Using the background and monthly averaged anomalies of  
 179 20 freely-run AOGCMs (with  $0.5^\circ \times 0.5^\circ \times 40$  levels resolution and no assimilation), we  
 180 generate ensemble members that are centered about the current background state. The ocean  
 181 observers are run for all the ensemble members, resulting in an ensemble of innovations (i.e.,  
 182 an ensemble of the departure of observations minus the ensemble member). These innova-  
 183 tions combined with the above calculated ensemble members are then used to perform an  
 184 LETKF analysis. Sea ice fraction (AICE) is replaced by concentrations calculated using the  
 185 NASA Team algorithm [*Cavaliere et al., 1996; Maslanik and Stroeve, 1999*] at the analysis  
 186 step in order to provide optimal ice fields. The coupled model is then rewound to the start of  
 187 the assimilation cycle to perform the corrector step, during which time the ocean temperature  
 188 and salinity increments are evenly applied to the ocean trajectory over the first 18 hours of  
 189 the corrector step to reduce any shocks to the system. The coupled system is then allowed to  
 190 evolve constrained by FPIT forcing and its sea surface temperature for the remainder of the  
 191 5-day segment. This process is then repeated over the next 5-day data assimilation window,  
 192 cycling over time.



193

**Figure 1.** Schematic of Coupled Data Assimilation Methodology

### 2.2.2 Ocean Data Assimilation Technique

The Ocean Data Assimilation System (ODAS) used by the GEOS S2S-2 system at the GMAO follows the Local Ensemble Transform Kalman Filter (LETKF) developed by *Penny et al* [2013] for ocean applications. Unlike *Penny et al* [2013], our ensemble members are derived from an already existing trajectory of a coupled model run that was computed without any data assimilation, that is, from a free-running model. Thus, our version of the assimilation procedure more closely resembles the Ensemble Optimal Interpolation (EnOI, e.g., *Keppenne et al.* [2008], *Karspeck et al.* [2013], *Vernieres et al.* [2012]). However, the GEOS-S2S-2 ODAS closely matches the LETKF for other aspects like the localized influence of an observation on the analysis. More details regarding the LETKF can be found in *Ott et al.* [2004], *Hunt et al.* [2007], and *Penny et al.* [2015].

The GEOS-S2S-2 ocean analysis includes an assimilation of various in situ profile observations summarized in Table 1. Tropical Atmosphere/Ocean (TAO), Prediction and Research Moored Array in the Atlantic (PIRATA), and Research Moored Array for African-Asian-Australian Monsoon Analysis (RAMA) and Prediction refer to fixed tropical mooring arrays that are designed to observe temperature and salinity at depth within the oceanic waveguide [*McPhaden et al.*, 2010] in the Pacific, Atlantic and Indian Oceans, respectively. Expendable Bathythermograph (XBT) data are instruments released from research cruises or volunteer observing ships and so are generally found in regions of repeat transects. Unlike most of the other profile data, XBT data typically only includes temperature observations. Conductivity, temperature, and depth (CTD) data are collected by cast from research cruises so are also generally sparse in nature. On the other hand, the major profile data source is from the Argo array [*Roemmich et al.*, 2009]. The Argo array is made of thousands of autonomous profiling Lagrangian floats that descend and ascend through the water column on a regular schedule (typically 10 days, 5m - 2000m), saving temperature, salinity and pressure observations as they travel. When the float surfaces, it sends its observations to the Global Telecommunications System and is made available at near-real time.

An example of typical data coverage for the near-real time 5-day assimilation cycle is shown in Figure 2 (in this case for December 21-25, 2017 run on December 29, 2017). Note that most of the spatial resolution comes from the Lagrangian drifters that make up the Argo array (59567 observations whose locations are shown by light blue dots in Figure 2) whereas much of the temporal coverage can be accounted for by the fixed moorings (e.g. TAO in the Pacific, PIRATA in the Atlantic, RAMA in the tropical Indian Ocean - 13530 total number of observations). For this work, the mooring data are averaged daily to reduce the high frequency signal found in the hourly mooring observations. Also note the lack of XBT and CTD data since these data are typically available about 2 months in arrears and so these data were not available to the near-real-time ODAS. It is also interesting to note that there are approximately 20% fewer salinity observations than temperature observations (compare Figure 2 left and middle panels for light blue dots) since salinity sensors are more likely to foul than temperature.

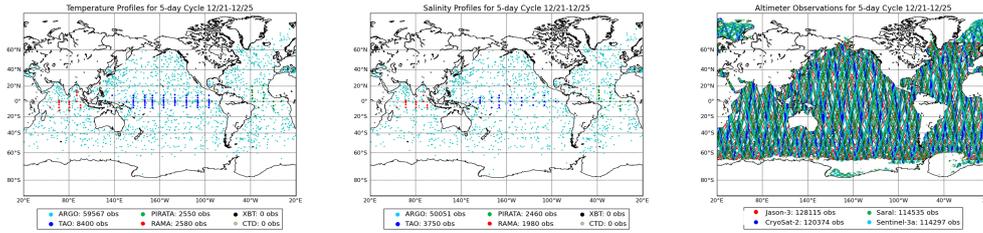
In addition to in situ observations, surface topography observations from satellite altimetry have been utilized to help determine the general ocean circulation, to study seasonal to decadal changes, and to improve global ocean and coupled model initialization. Sea level anomaly is defined as the sea surface height above a mean sea surface (MSS) that is defined over many repeat tracks and independently for each satellite (<https://www.aviso.altimetry.fr/en/data/products/auxiliary-products/mss.html>). The absolute dynamic topography (ADT) is then the sea level anomaly added to the mean dynamic topography (MDT) which is calculated using a combination of gravity missions (GOCE, GRACE), all available altimetry, and in situ data over 1993-2012 (<https://www.aviso.altimetry.fr/en/data/products/auxiliary-products/mdt/mdt-description.html>). Since TOPEX/Poseidon (launched in 1992), a series of altimeters have continuously provided ADT observations with varying estimated accuracy of 4 cm [*Shum et al.*, 1995]. Typically the joint US/French series (TOPEX, Jason 1, 2, and 3) have repeat orbits designed to

Instrument	INST_ERROR			Data Coverage		Availability/ Repeat	Source:
	T (°C)	S (psu)	SLA (m)	Start	End		
TAO	0.02	0.1		1980	present	daily	PMEL ( <a href="http://taopmelftp@ftp.pmel.noaa.gov/ascii/sites/daily">http://taopmelftp@ftp.pmel.noaa.gov/ascii/sites/daily</a> )
PIRATA	0.02	0.1		1997	present	daily	"
RAMA	0.09	0.1		2005	present	daily	"
XBT	0.1	0.1		Prior to 1980	Present – ~1 month	Sparse – VOS*/SOO or research	UK Metoffice ( <a href="https://www.metoffice.gov.uk/hadobs/en4/download-en4-2.0.html">https://www.metoffice.gov.uk/hadobs/en4/download-en4-2.0.html</a> )
CTD	0.003	0.02		Prior to 1980	Present – ~1 month	Sparse – research (high vertical resolution)	"
ARGO	0.005	0.02		1996	present	10 day cycle - lagrangian	USGODAE ( <a href="http://www.usgodae.org/pub/outgoing/argo/geo/">http://www.usgodae.org/pub/outgoing/argo/geo/</a> )
Topex			0.02	09/25/92	04/24/02	10day repeat	Copernicus ( <a href="ftp.sltac.cls.fr/Core/SEALEVEL_GLO_PHY_L3_NRT_OBSERVATIONS_008_044">ftp.sltac.cls.fr/Core/SEALEVEL_GLO_PHY_L3_NRT_OBSERVATIONS_008_044</a> )
ERS-1+2			0.02	10/23/92	10/08/02	35day repeat	"
Geosat FO			0.02	01/07/00	09/07/08	17 day repeat	"
Jason1	0.02			04/24/02	10/19/08	10 day repeat	"
Jason2	0.02			10/19/08	09/12/16	10 day repeat	"
Jason3	0.02			08/22/16	present	10 day repeat	"
Envisat			0.02	10/26/10	04/08/12	35 day repeat	"
Cryosat-2			0.02	01/28/11	present	369 day repeat with 3, 29, 85 sub-repeat	"
Saral			0.02	03/14/13	present	35 day repeat	"
HY-2A			0.02	04/12/14	present	14 day repeat	"
Sentinel 3A			0.02	02/29/16	present	27 day repeat	"

221 **Table 1.** Table showing the estimated instrumental error, period and source for all data used in the ODAS.  
 222 The altimeter products were produced by SSALTO/DUACS and distributed by AVISO, with support from  
 223 CNES (<http://www.aviso.altimetry.fr/duacs/>).

253 measure the complete globe every 10 days. In contrast, the European satellites have 35-day  
 254 exact repeat orbits (see Table 1 for details).

255 A unique aspect of this ODAS is that absolute dynamic topography (ADT) is assimilated into the S2S-v2.1 using the same schedule/technique as for the in situ data. Because  
 256 of the sheer volume of the data, ADT data are thinned along track prior to assimilation. A  
 257 Gaussian weighted mean is calculated for the central point of +/- 10 along-track observations  
 258 using a decorrelation scale of 1000 km. This mean is then output for assimilation. The observational error for assimilation for this point is also calculated and output as the standard  
 259 deviation using the weighted mean and the Gaussian-weighted +/- 10 surrounding along-track  
 260 points. Within the ODAS, the ADT observational error is minimized to 0.1 m and an  
 261 additional term is added to increase the ADT observational error away from the equator accounting for the Rossby deformation radius. This term linearly rises from 0.0 m at the equator  
 262 to 0.1 m at 90° and the resulting observational error is then scaled by a factor which was  
 263 tuned to produce optimal fields. Finally, the mean of all ADT observations for the assimilation  
 264 period is removed prior to assimilation so that no mass is added to the solution. The  
 265 horizontal localization is identical to that used for the profile data described above. Finally, if  
 266  
 267  
 268



237 **Figure 2.** Data coverage for a typical 5-day assimilation (this case is for 5 day cycle centered on Dec.  
 238 23, 2017 extracted on Dec 29, 2017). Left panel shows all the profile data for temperature. Middle panel  
 239 shows salinity profile data and right panel shows the data coverage for ADT data. For the profile data, the dot  
 240 corresponds to the profile location and the number of observations in the key includes all model depths.

269 any ADT observation departure from mean background is greater than 1.0 m then the obser-  
 270 vation is removed from consideration.

271 The data coverage of ADT data for a typical 5-day operational ODAS is shown in Fig-  
 272 ure 2. The large volume of satellite ADT data is obvious even with subsampling the ADT  
 273 data as described above. Relatively large gaps “diamonds” in the coverage occur  $5^{\circ}$  to  $40^{\circ}$   
 274 off the equator due to the various orbit orientations. Jason-3 data (red dots) cuts off at approx-  
 275 imately  $66^{\circ}$  due to the high repeat orbital frequency (i.e. 10 days) and concomitant satellite  
 276 orbit inclination. Other satellites with higher inclination orbits observe further north and  
 277 south (e.g. CryoSat2 -  $92^{\circ}$ , Saral -  $98.5^{\circ}$  and Sentinel 3A -  $98.6^{\circ}$  inclination). Data gaps off  
 278 Greenland, Labrador Sea, Hudson Bay, and Barents Sea in the north are due to ice coverage.  
 279 In addition, the ice extent is clearly visible in the Southern Ocean around Antarctica. The  
 280 valid data in the Ross Sea and eastern Weddell Sea is associated with open water of ice-sheet  
 281 melting in southern summer. In any case, satellite derived ADT measurements provide a cop-  
 282 ious amount of observations for the ODAS.

283 Prior to assimilation into the ODAS, observations are preprocessed to perform quality  
 284 control and to limit the data to be ingested. All profile data types are treated in the same way.  
 285 First each profile is thinned to the model depth by simply averaging all the profile informa-  
 286 tion within the model layer and these data are then assigned to the model layer depth. Next,  
 287 the resulting data are checked against a climatology formulated using all available in situ obser-  
 288 vations from the World Ocean Atlas 2013 for temperature [Locarnini *et al.*, 2013] and for  
 289 salinity [Zweng *et al.*, 2013]. Profile data at depth are flagged if the profile observation is  
 290 more than 6 standard deviations away from the corresponding observation climatology. For  
 291 the LETKF analysis, data are assigned observational error depending on the depth gradient  
 292 of the observation. For the S2S-v2.1 ODAS,  $dT/dz$  and  $dS/dz$  are first required to be greater  
 293 than or equal to  $1.e^{-3} \text{ }^{\circ}\text{C/m}$  and  $\text{psu/m}$ , respectively. Then they are scaled by a factor, deter-  
 294 mined by a series sensitivity studies, to give the optimal profile observation error. In this way  
 295 the observational error is greatest at the depth of maximum gradient such as within the ther-  
 296 mocline. As a final large-scale error test, any observation with background departure greater  
 297 than  $10^{\circ} \text{C}$  for temperature and 10 psu for salinity are tossed out.

298 The LETKF solves the analysis states in a local volume centered on each model grid  
 299 point and is applied on a regular grid ( $0.5^{\circ} \times 0.5^{\circ} \times 40$  levels). In the S2S-v2.1 formulation of  
 300 the LETKF, vertical localization is turned off for profile data. This has the benefit of calcu-  
 301 lating the analysis only once (as opposed to 40 times) and unlike the previous ODAS system  
 302 [Vernieres *et al.*, 2012] unique vertical localization profiles for each observation type are no  
 303 longer applied. This technique has the additional benefit of allowing assimilation of vertical  
 304 profiles and satellite altimetry data within a single process. The horizontal localization func-



<b><u>OCEAN/ICE MODEL</u></b>	<b>MOM4.1</b> (Griffes et al., 2005), 0.5°, CICE 4.0 (Hunke and Lipscomb, 2008), 40 layers down to ~4500m	<b>MOM5.0</b> (Griffes et al., 2012), 0.5° CICE 4.0, 40 layers down to ~4500m
<b><u>ASSIM TECHNIQUE</u></b>	<b>SAFE/EnOI</b> (Keppenne et al, 2014/ Oke et al., 2010, Wan et al. 2010), <b>5-day IAU</b>	<b>LETKF</b> (Penny et al., 2013), <b>18 hour IAU</b>
<b><u>FORECAST ERROR</u></b>	Pre-specified static forecast error cov. from <b>leading EOFs</b> of an ensemble of forecast anom (wrt climate drift) from AOCGM	Estimate <b>evolving errors</b> using monthly averaged anom from 20 freely coupled AOCGMs re-centered about analysis.
<b><u>DATA</u></b>	<b>10-day window</b> , binned to model level, reject if $>6\sigma$ from WOA09, <b>obs. error prescribed</b> to observation and type, <b>decorrelation scales</b> x, y, z, t function of variable, <b>unique vertical localization</b> factors applied for each observation and type	<b>5-day window</b> , binned to model level, reject if $>6\sigma$ from WOA13, <b>obs. error from <math>\frac{dT.S}{d\Delta T}</math> or <math>\frac{dT.S}{d\Delta s}</math></b> or $\frac{d(\text{along track dist.})}{d\Delta T}$ , <b>horizontal localization</b> applied $\propto$ Rossby deform radius, <b>no vertical localization</b> applied
<b><u>ASSIM SEQUENCE</u></b> (*SAFE, *EnOI)	Tz, Sz Clim* SSS Clim* SST* Tz' Sz' AICE	Tz, Sz, ADT
<b><u>RELAXATION VARS</u></b>	None	SST (1day), AICE (insertion)
<b><u>REPLAY FORCING</u></b>	<b>MERRA</b> (Rienecker et al., 2011) corrected using GPCP (<9/09), CMAP (9/09-present)	<b>"MERRA2-like"</b> (FPIT) (Gelaro et al., 2017) corrected using CMAP precip.

328 **Table 2.** Table highlighting the differences between the setup for the S2S-v1 (middle column) versus S2S-  
329 v2.1 (right column).

305 tion is used to scale the observational errors such that observations nearer the central model  
306 point result in higher localization weighting function. In addition, the horizontal localization  
307 function accounts for the larger Rossby radius of deformation near the equator. This radius  
308 varies from 240 km near the equator to less than 10 km near the poles [Chelton et al., 1998].  
309 In practice, the horizontal localization function is parameterized as a Gaussian and as a func-  
310 tion of latitude with 1 standard deviation of 3.6° at the equator and 1.8° at the poles. Thus,  
311 the impact degrades as the observation point is further from the central point and as the ob-  
312 servation latitude increases.

313 There are many differences between the ocean analysis methods in the GEOS S2S-1  
314 Borovikov et al. [2017] and GEOS S2S-2 systems. The major differences are summarized  
315 and highlighted in Table 2. For the current system, initial conditions and verification for the  
316 land and atmosphere are provided by the NASA FPIT reanalysis, an improved atmospheric  
317 forcing field over MERRA which was used to force GEOS S2S-1 (**NEED REFERENCE FOR  
318 THIS**). In GEOS S2S Version 2 the observations are incorporated into the ocean state using  
319 a 5-day assimilation cycle and the Local Ensemble Transform Kalman Filter (LETKF) us-  
320 ing 20 ensemble members (Vernieres et al. [2012]). The advantage of this ensemble Kalman  
321 Filter over a less expensive deterministic filter such as the GEOS S2S-1 SAFE/EnOI (Kep-  
322 penne et al. [2014], Oke et al. [2010]) techniques is that it allows the error covariances to  
323 evolve with the seasonal cycle and the phase of ENSO. Another clear advantage of the cur-  
324 rent system is that GEOS S2S-2 assimilates all available satellite altimetry whereas the pre-  
325 vious system did not assimilate any sea level in the production system. In section 5 we will  
326 show some key metrics documenting improvements in the current (GEOS S2S-2) versus the  
327 old production system (GEOS S2S-1).

### 3 Experiments and Initialization Method

In this study, we examine the results of four sets of seasonal and subseasonal forecasts using the new GEOS-S2S\_2.1 system, a long-term free running simulation with the GEOS S2S-2 AOGCM, and the AO-CDAS itself. The four sets of forecasts are: 1) near real-time seasonal forecasts, 2) retrospective seasonal forecasts, 3) near real-time sub-seasonal forecasts, and 4) retrospective subseasonal forecasts. The long-term simulation is a 50-year long atmosphere-ocean coupled climate simulation with GEOS-S2S\_2.1, which is a "perpetual 2000" simulation, where the external climate forcing is fixed at that of year 2000. GEOS-S2S\_2.1 is also utilized in producing the ocean analysis dataset (2012-present), that is used to initialize the seasonal and subseasonal near real-time forecasts.

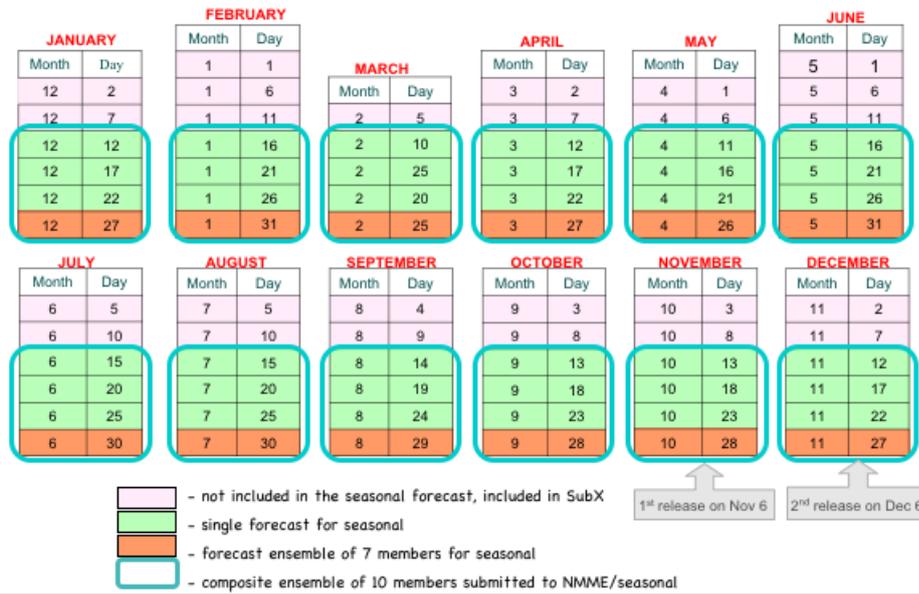
Here we provide a description of the experimental set-up of the seasonal retrospective forecasts and forecasts. Historically, owing to the availability of the GMAO ocean data assimilation products, the GMAO forecasts were initialized on a fixed set of calendar dates. These begin on Jan 1, and are phased 5 days apart, thus producing a total of 72 start dates per year (Fig 3). In the new system, we follow the same start date calendar, although seasonal forecasts and reforecasts are limited to the last 4 start dates of the month (green and orange boxes in Fig 3). For the retrospective forecasts, no perturbations on initial conditions are employed, rather the lagged start dates form an ensemble of 4 for any month. A set of seasonal reforecasts are conducted for a period of 36 years (1981-2016). A suite of 5-day long ocean data assimilation runs were produced for 1981-2016, initialized at 5 day intervals, in order to generate initial conditions for the retrospective seasonal and subseasonal forecasts.

For near real-time seasonal and subseasonal forecasts, the atmosphere is initialized from GMAO's real-time forward processing for instrument teams (FPIT) analysis (*Lucchessi et al.* [2016]), and the ocean and sea ice initial conditions are taken directly from a continuous GEOS-S2S-2\_1 AODAS run initialized in 2012 with MERRA-Ocean fields. *In the land fields, observed precipitation values are incorporated by ....* As compared to the retrospective forecasts, for the near-real-time suite an additional 6 ensemble members are generated around the 4th member (last start date in each month) (orange box in Fig 3), thus producing a total of 10 ensemble members (4 unperturbed and 6 perturbed). The method to perturb initial conditions is based on the difference between two analysis states 5 days apart. The perturbations are re-scaled and the magnitude of the norm reduced to approximately 10 percent of the natural variability of SST over the norm region (i.e. 0.48C); the region for defining the norm is tropical Pacific domain over 120W-90W, and 10S-10N. The rescaling norm is the RMS difference of the instantaneous sea surface temperatures (SSTs) from two analyses 5 days apart. The variables perturbed are on ocean model grid - 3D temperature, salinity and ocean velocities, surface temperature, sea level and **frazil**, ice velocity and strain components, ice strength, extent U mask and stress tensor components; on atmospheric grid - wind components, potential temperature and specific humidity; on tiles - skin temperature, salinity and depth. Both the near real-time forecasts and retrospective forecasts are run for a period of 9 months.

The subseasonal retrospective forecasts are performed for 17 years (1999-2015). The reforecasts are initialized every 5 days (pink, green and orange boxes in Fig 3) with a total of 73 start dates per year, with 4 ensemble members per start date. Here, one ensemble member consists of unperturbed initial conditions and the remaining three are generated by perturbing the atmospheric initial conditions in horizontal winds, potential temperature and specific humidity. The perturbations are computed as scaled differences ( $\pm (x-y)/8$ ) between two arbitrary atmospheric states ( $x, y$ ) taken 1 day apart. The somewhat arbitrary scaling factor of 1/8 is chosen in an attempt to produce perturbations that are of size consistent with initial errors typically found in numerical weather prediction models. The initial conditions, as for the seasonal forecasts, are based on a series of 5-day long ocean data assimilation runs. The near real-time subseasonal forecasts are conducted in a similar manner to the retrospective forecasts, with initialization in every 5 days, and 4 ensemble members around each start date. Both the near real-time forecasts and retrospective forecasts are run for a period of 45 days.



## Sub/Seasonal Forecast/Hindcast Schedule



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**Figure 3.** Schedule of Forecasts and Hindcasts

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## 4 Climate of Coupled Model

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### 4.1 Mean Atmospheric Climate

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The examination of the results of simulations with GEOS S2S-2 begins with the assessment of the 50-year mean climate and a comparison against the previous version of the model (GEOS S2S-1). This is the climate state towards which the shorter term simulations are drifting at different rates, and as such its assessment is critical to establishing the fidelity of the model. In this section we focus on the quality of the atmospheric component of the GEOS S2S-2 model's long-term climate. Results are presented to assess the quality of the circulation, hydrological cycle and radiative balance, as reflected in the December-January-February (DJF) and June-July-August (JJA) mean circulation, stationary waves, mean wind, and atmospheric transients, as well as precipitation, net radiation and surface air temperature.

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Figure 10 shows....

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Figure 6 shows that the mean error in the stationary waves (as shown by the 300 hPa eddy heights) is substantially reduced in the new model relative to the old model for both seasons and both hemispheres. In particular, the weak boreal winter stationary waves in the old model (especially over the North Pacific/North American region, Fig. 6a), are now stronger and closer to the observed as seen from the smaller biases (Fig. 6c). During JJA the new model also has reduced biases particularly over Eurasia (Figures 6b and 6d).

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The simulated 200 mb zonal winds (Figure 7) show some improvements and some degradations in GEOS S2S Version 2 relative to Version 1. While the middle and high latitudes generally show smaller errors for Version 2, reflecting improvements in the middle latitude jets, there is a subtropical westerly wind bias in the new model in both hemispheres and during both seasons, and especially so for boreal summer. Despite these subtropical zonal wind biases, there are substantial improvements in the middle and high latitude tran-

408 sients (shown in Fig. 8) that we argue are tied to the above-noted improvements in the middle  
409 and high latitude zonal winds. In particular, the old GEOS S2S-1 model had weak boreal  
410 summer middle latitude storm tracks (see the negative bias in Fig. 8b) linked to the weak  
411 North Pacific and North Atlantic jets (Fig. 7b), that are now much improved. The new model  
412 does show somewhat excessive wintertime transients in the upper troposphere subtropics,  
413 associated with the excessive subtropical westerlies (Figs. 8c and 8d). Figure 8 also shows  
414 improvements in the stationary wave variances, reflecting the improvements to the station-  
415 ary waves shown previously (Fig. 6). The new model also has improved lower tropospheric  
416 northward moisture transport (Figure 9) during both seasons and in both hemispheres. Dur-  
417 ing DJF the excessive northward transport in the southern hemisphere (Fig. 9c) is almost  
418 completely eliminated in the new model. The negative biases in the North Pacific and North  
419 Atlantic are also eliminated but with some positive biases now occurring in the subtropics.  
420 During JJA the moisture fluxes are much improved throughout much of the globe, with the  
421 new model showing only weak negative biases in most regions, except for a few isolated re-  
422 gions such as over the North Pacific just off the east coast of Asia.

423 We next examine the biases in precipitation and surface air temperature, that are two  
424 quantities that have considerable practical importance since they are the quantities for which  
425 society would likely benefit most from improvements in skill. The precipitation biases (Fig-  
426 ure 11) show a mix of both improvements and some degradation. During DJF the new model  
427 shows generally reduced biases with the main exception being the large positive bias just  
428 north of the equator in the Pacific (Figure 11c). There is also little improvement over the  
429 Indian Ocean. There is much less improvement during JJA, especially in the tropics with  
430 a much increased positive bias in the Atlantic and a much more pronounced split ITCZ in  
431 the Pacific (Figure 11d). There is also much less rain over India, reflecting a lack of sum-  
432 mer monsoon rainfall in the new model. The main improvements include the elimination of  
433 the excessive precipitation over Tibet, and much improved precipitation over the NH storm  
434 tracks, presumably reflecting the improved summer transients mentioned earlier (Figures 11b  
435 and d).

436 Long term mean precipitation patterns in GEOS S2S-2\_1 show some improvement and  
437 some degradation relative to GEOS S2S-1\_0. Figure 11 shows the new and old AOGCM  
438 simulation precipitation relative to estimates from the Global Precipitation Climatology  
439 Project (GPCP, *Huffman et al.* [2009]). The excessive precipitation over high topography  
440 seen in the results from the old system in Figure 11d over the Andes, the Maritime Continent  
441 and the Tibetan Plateau is still present in Figure 11c, but is reduced by more than a factor of  
442 2. In the tropical Pacific, however, the unrealistic precipitation minimum along the equator is  
443 exacerbated in the results using the new GEOS-S2S-2\_1 AOGCM.

444 Before turning to the surface temperature evaluation, the net radiation at the surface is  
445 examined, as errors in the net radiation are a dominant source of error in surface tempera-  
446 ture. The earth is assumed to be in approximate radiative balance, meaning that the globally  
447 averaged temperature is nearly constant during the year. The global net radiation at the top  
448 of the atmosphere, therefore, which represents the balance between the net incoming solar  
449 and net outgoing terrestrial radiation, is close to zero. In the GEOS S2S-2 simulation the bal-  
450 ance is held to within approximately  $1 \text{ W m}^{-2}$ . The horizontal distribution of the different  
451 components of the radiation budget have important implications for the atmospheric general  
452 circulation patterns.

453 The distribution of the net TOA radiation, in particular the latitudinal gradients, is as-  
454 sociated with the net driving energy for the atmospheric and oceanic general circulations.  
455 The zonal mean cross sections, figure 4, show a pattern that follows the net shortwave, which  
456 is a positive maximum in the summertime subtropics, decreasing towards the summer pole  
457 and towards the winter hemisphere, crossing zero in the winter subtropics, descending to a  
458 negative minimum at the dark winter polar latitudes. The strongest north-south gradients,  
459 which imply the strongest north-south heat transports, are in the winter hemisphere. The fig-  
460 ure shows that GEOS S2S-2 simulation matches the general distribution of the net radiation

quite well. The errors in the shortwave and the errors in the longwave compensate and the resulting net radiation matches the CERES estimate.

Surface radiative balance is shown in Figure 5....

Finally we turn to the surface air temperature over land (Figure ???). The new model shows overall much improved (reduced) biases in both seasons. The strong negative biases during DJF in NH high latitudes in the old model are for the most eliminated (cf. Figs 6a and c). The new model does show some tendency for increased positive biases during DJF especially in the SH. During JJA, the new model has much reduced positive biases over northern Eurasia and reduced negative biases over Greenland, with however some increase in the positive biases in the tropics and SH as well as over the Indian subcontinent (cf. Figs 6b and d).

In summary, the biases in the new model are overall much improved throughout the middle and high latitudes, both for the dynamical quantities considered here and the precipitation, net radiation and surface temperature. The main problems in the new model appear to be linked to excessive tropical precipitation, and that includes the excessive subtropical westerlies and associated exceptionally warm tropical upper tropospheric temperatures (not shown). It is noteworthy that the tropical precipitation biases (and weak precipitation over India) are much reduced if not absent from the new model when run uncoupled (forced with observed SST), indicating these are errors associated with coupled processes. As such, we must also look at the model's ocean climate including the surface fluxes to help us understand the nature of these biases. This is the subject of the next subsection.

## 4.2 Mean Ocean Climate

The long term mean climate of the AOGCM is examined in comparison to other observationally based estimates of various fields. Figure 13 shows a comparison of the old and new S2S AOGCM long term mean sea surface temperature (SST), using the Reynolds SST analysis for reference. The large region of saturated purple shading in Figure 13d near Greenland and the Labrador Sea are absent in the S2S-2\_1 result seen in Figure 13c. In addition, other regions of cold bias greater than 2 ° C, in the northern Pacific and Atlantic and southern Pacific oceans are also absent in the simulation with the new system. Warm bias on the order of 2 ° C close to the west coast of Africa and South America seen in 13d are also removed in the new system (13d). Most of the changes in SST represent clear improvements in GEOS S2S-2 relative to GEOS S2S-1. **NEED TO EXPLAIN WHY**

**need more stuff here**

Figure 14 shows.....

Figure 15 shows.....

Figure 16 shows.....

## 4.3 Climate Variability

A sub/seasonal forecast system's success is often viewed in terms of its ability to predict the evolution of climatic modes such as El Nino and the Pacific Decadal Oscillation (PDO) — components of the Earth system that have significant intrinsic predictability at seasonal time scales. Much of the societal value of a forecast, however, is arguably tied to its performance in continental population centers, which can be quite distant from the SST patterns representing such modes. A desirable characteristic for a forecast system is indeed the ability to capture realistically any teleconnections that might exist between the predictable modes over the ocean and remote continental meteorology.

This is evaluated in Figure 17, using an approach described by Collow et al. (2017). Figure 17a shows the relationship between an observed index of the PDO during DJF and

the observed DJF near-surface air temperature (T2M). The PDO indices were extracted from the Physical Science Division of NOAA's Earth Science Research Laboratory (ESRL, <https://www.esrl.noaa.gov/psd/data/climateindices/list>), while the observed air temperatures were estimated with MERRA-2. The observations indicate a swath of negative correlation from the northeastern US into eastern Mexico. When the same calculation is performed with output from a long-term, free-running coupled simulation using the model underlying the old forecast system (with the PDO index computed from the simulated SSTs using ESRL's method), negative correlations are again seen in the eastern US, but unrealistic values appear in the center of the country, and underestimated values are seen along the eastern coast (Figure 17b). In a parallel coupled simulation using the model underlying the new system, the spatial pattern of the negative correlations is generally improved, though the magnitudes of the correlations along the east coast are still too weak.

Figures 17d-f show corresponding results for the Nino3.4 index. The observed teleconnection pattern (Figure 17d; the observed Nino3.4 was also extracted from the ESRL website) shows positive correlations in the northern US and southern Canada and negative correlations in Mexico and Texas. The simulated teleconnections in both the old system (Figure 17e) and the new system (Figure 17f) clearly overestimate the spatial extent of the negative correlations and miss the positive ones. Results for precipitation, however, are more encouraging. Gauge-based precipitation observations (as processed in MERRA-2; see Reichle et al. (2017)) show a positive correlation with Nino3.4 index in the southern tier of the US and patches of negative correlation along the northern border (Figure 17g). Both the old (Figure 17h) and new (Figure 17i) systems capture some of the eastern segment of the positive correlations, and the new system appears to place the negative patches to the north in roughly the right place.

## 5 Ocean Data Assimilation Results - Comparison of S2S-1 and S2S-2

In this section we will evaluate the S2S-1 and the S2S-2 ocean data assimilation system (ODAS) results. The quality of the ODAS has direct implications for the fidelity of the forecasts that are initialized with the ODAS fields. MORE HERE??

We assess improvements in our current coupled system by comparing a sampling of ocean metrics against those from the previous system. For sea level and geostrophic currents, the two sets of reanalyses are compared against the multi-gridded altimetry product of AVISO [2013]. S2S-2 has an overall reduced bias with respect to observations for nearly all regions. This is not surprising considering the fact that the S2S-2 ODAS assimilates sea level whereas the S2S-1 ODAS did not. The improvement with S2S-2 is most dramatic in the western boundary current region of the Kuroshio, Gulf Stream and Brazil Currents. In these regions, assimilation of sea level data is critical for improving the character and location of these turbulent regions. As an example, Figure 18 shows the zonal current speed for August 2017. The bottom right figure shows the observations from the multi-product AVISO sea level. The prominent features of the Loop Current entering the Gulf of Mexico and the eddies and meanders of the Gulf Stream off the east coast of North America are clearly evident in observations. On the other hand, the S2S-v1.0 (top right) barely shows the Loop Current and the Gulf Stream has no eddies nor meanders and it exits the coast too far north as compared to observations. The S2S-v2.1 better reproduces the amplitude and location of the observations (top right). The S2S-v2.1 has a much more realistic pattern of eddies and meanders in the Gulf Stream and the amplitude and Loop current is much better reproduced in the S2S-v2.1 as opposed to S2S-v1.0. In addition, the Gulf Stream exit into the North Atlantic is much better modeled in the S2S-v2.1 experiment. Although the exact locations of the meanders and eddies for the S2S-v2.1 don't exactly match the observed locations, the general character of the S2S-v2.1 experiment better represents the transport of observations. This improvement in the western boundary current is likely due to the combination of the improved forcing of MERRA2 versus MERRA and the assimilation of satellite altimetry for S2S-v2.1.

586 The location and amplitude of the western boundary currents have important conse-  
 587 quences for climate as measured by global heat conveyor belt indices. One such index is the  
 588 RAPID array along 26.5°N that measures the Atlantic Meridional Overturning Circulation  
 589 (AMOC). Moorings stretching across the Atlantic at 26.5°N measure temperature, salin-  
 590 ity and currents and can thus measure the transport of warm water northward (via the Gulf  
 591 Stream) and cool water southward (via the North Atlantic deep circulation). Figure 19 top  
 592 shows that the AMOC for the S2S-v1.0 is consistently weaker than observed. On the other  
 593 hand, the S2S-v2.1 is initially too strong compared to observed values. However, as the ex-  
 594 periment spins down, the S2S-v2.1 reanalysis settles to match the magnitude of observations.  
 595 In addition, the interannual variability of the S2S-v2.1 looks more realistic with respect to  
 596 observed values as compared to the S2S-v1.0.

597 Another major region of western boundary current transport of the global heat con-  
 598 veyer belt is the Indonesian Throughflow (ITF). Warm, fresh water is transported through  
 599 the ITF due to consistent pressure head from the Pacific to the Indian Ocean. Eleven moor-  
 600 ings were deployed across the entrance (Makassar Strait, Lifamatola Passage but not Halma-  
 601 hera) and exit regions (Lombok, Ombai, and Timor) of the ITF from 2004-2006 and are dis-  
 602 persed to accurately measure each passage's contribution to the ITF (*Sprintall et al.* [2009]).  
 603 In addition, various studies attempted to directly measure the flow of the ITF and estimate  
 604 the interannual variability. For example, *Meyers et al.* [1995] measured the mean ITF us-  
 605 ing the geostrophic transport calculated from the IX01 WOCE XBT data (Fremantle-Sunda  
 606 Straits). Here we calculate an index of the ITF using our gridded optimal interpolation of ob-  
 607 served temperature and salinity (*Carton* [1989]), convert temperature and salinity to dynamic  
 608 height, and then calculate geostrophic currents. The transport is then estimated the across  
 609 114°E between 21°S and 9°S (closely matching the IX01 line). The good correspondence  
 610 between the INSTANT measurements (red dash line in Figure 19 bottom) and our ITF es-  
 611 timates (red solid line) demonstrates the fidelity of this technique. Figure 19 bottom shows  
 612 that the S2S-v1.0 reanalysis badly underestimates the transport of the ITF. The mean for  
 613 S2S-v1.0 is about -5 Sv whereas observed values are estimated at -15 Sv (INSTANT) and  
 614 -14 Sv by *Wijffels et al.* [2008] using QuikScat winds and the Island Rule of *Godfrey* [1989].  
 615 On the other hand, the S2S-v2.1 closely matches the mean, seasonal cycle, and the interan-  
 616 nual variability of the observations. The ITF transport of the S2S-v2.1 clearly outperforms  
 617 the S2S-v1.0 values.

626 Finally we assess the differences between S2S.v1.0 and S2S-v2.1 for the large-scale  
 627 oceanic Kelvin and Rossby waves for the equatorial Pacific. These waves are instrumental for  
 628 proper attribution of the buildup and recharge stages of ENSO, respectively (e.g. *Jin* [1997]).  
 629 In Figure 20, the model and observed sea level data sets are first converted to geostrophic  
 630 currents (*Picaut and Tournier* [1991]) then the Kelvin and Rossby amplitudes are calculated  
 631 using the technique of *Decroix et al.* [1994]. The top left panel shows the observed west-  
 632 to-east propagating Kelvin wave signal for 2013-2015. Early in the time series, negative  
 633 (blue) Kelvin waves represent the upwelling associated with the weak 2013 La Niña. The  
 634 downwelling (red) signals of the 2015 El Niño are evident starting from January 2015 and  
 635 each successive Kelvin wave increases in magnitude as the Bjerknes feedback becomes en-  
 636 hanced throughout the buildup of this big event (see e.g. *Santoso et al.* [2015] for details of  
 637 this event). The amplitude and timing of these Kelvin waves are well reproduced by the S2S-  
 638 v2.1 experiment (top middle panel). On the other hand, the S2S-v1.0 shows overall weaker  
 639 Kelvin wave amplitude throughout the period (right top panel). For example, the big Kelvin  
 640 wave in summer 2015 is roughly 30% smaller for the S2S-v1.0 than for S2S-v2.1 example.  
 641 For the Rossby waves (Figure 20 bottom), the lack of amplitude for the S2S-v1.0 is even  
 642 more evident. The big upwelling (downwelling) Rossby wave in early 2013 (2015) is accu-  
 643 rately reproduced by the S2S-v2.1 system (middle bottom) whereas the S2S-v1.0 badly un-  
 644 derestimates these signals. For example, the upwelling in spring of 2013 reaches -0.3 m/s for  
 645 observations and S2S-v2.1 but the S2S-v1.0 only peaks at -0.15 m/s.

In summary, almost all ocean variables examined were improved for the S2S-v2.1 relative to S2S-v1.0. SST and SSS biases were reduced (especially off the equator and in the North Atlantic, respectively) but SSS was somewhat degraded over Indonesia and the Amazon plume. Assimilation of SL in S2S-v2.1 improves western boundary currents. For example, the amplitude, location, and character of Loop Current and the Gulf Stream and both were more realistic with respect to S2S-v1.0. The large scale meridional (AMOC) and zonal (ITF) heat transport indices were significantly improved in S2S-v2.1. The amplitude of the Large-scale Kelvin and Rossby waves were simulated well with S2S-v2.1 whereas S2S-v1.0 badly underestimated the El Niño and La Niña forcing. Improvements are most likely due to sea level assimilation and better forcing (MERRA2 versus MERRA) for S2S-v2.1 as compared to S2S-v1.0.

## 6 Seasonal and Subseasonal Forecast Assessment

### Results of retrospective seasonal forecasts....

While forecast assessment should in general include both a deterministic and probabilistic evaluation, the relatively small ensemble size of our seasonal retrospective forecasts limits what we can do to assess the quality of the ensemble (e.g., reliability diagram, ROC, Brier skill score). As such, we focus here primarily on deterministic measures involving the ensemble mean such as, anomaly correlation, rms, and phenomena-based compositing, though we do provide an initial assessment of the ensemble spread compared to that of the previous system. We begin with a look at the climate drift, keeping in mind that the forecast skill evaluation is done for the anomalies (after removing the climate drift).

### 6.1 Climate Drift

#### Climate drift (SST, T2m over land, precipitation) – time series of AMOC

Taken from Anna's paper, needs to be rephrased.

Forecast drift is an artifact of the imperfect models. For the seasonal forecast it is necessary to properly account for the drift and calibrate the forecast accordingly. A complete set of retrospective forecasts for the entire training period are required to consistently de-trend the forecast. Following the convention established by Stockdale (1997) and others the drift is calculated as the average of these hindcasts from 1981-2010. It is subsequently subtracted from the production forecasts. For the S2S-2.1 a single hindcast was computed on each date, while for the S2S-1.0 multiple hindcasts with perturbed initial conditions we run on the dates corresponding to the forecasts with multiple ensemble members; the same perturbations techniques were used for hindcasts as for the forecasts. For the comparison of the forecast drifts and evaluation of forecast skill only the individual hindcasts done on the same dates (4 per month) were used from both systems.

Figures 21 and 22 show the SST seasonal mean error at 1, 3 and 6 month leads. From the west to east across the equatorial Pacific, the amplitude of the Niño 4 bias is reduced in S2S\_2.1 for all initialization times for all leads; in Niño 3.4 the late fall and early winter bias is smaller in S2S\_2.1 for all leads, and is generally within 0.5°C, while in S2S\_1.0 the bias reached -2°C in DJF, in spring and summer the bias is similar in both systems. In Niño3 region the cold bias in S2S\_2.1 lingers from February through early summer, while in S2S\_1.0 it is the largest in March, in in summer the bias is near 0°C. The greatest difference between the two systems occurs in the eastern equatorial Pacific Ocean, apparent in Niño1, Niño2 and the combined Niño1+2 regions SST indices. Figure 23 shows.....

Talk about different AGCM clouds here.



## 6.2 Forecast skill at subseasonal time scales: Tropical intraseasonal variability

Figure 24 shows bivariate correlation of Real-time Multivariate MJO (Real-time multivariate MJO (RMM)) indices between reforecasts (1999-2016) and MERRA-2 as a function of the forecast lead. The RMM indices are derived from the zonal wind at 850hPa and 200hPa and outgoing longwave radiation following the method addressed in [Wheeler and Hendon, 2004] and [Gottschalck et al., 2010]. The result presents that, at short lead (say 1-10 day lead), correlation is greater than 0.85 at all initial condition month. At inter-mediate lead, correlations are generally greater than 0.75, 0.65, and 0.55 at 15, 20 and 25 day lead, respectively. Prediction skill at long lead is particularly higher in summer from June through September, exceeding correlations of 0.5 even at 40 day lead. We compare this prediction skill with those identified from the other prediction models. A number of different models have had a difficulty in forecasting the MJO with correlation reaching 0.5 beyond 25 day lead (e.g., Fig. 1 in [Saha et al., 2014] and Fig. 2 in [Lim et al., 2018]). Our model for the MJO prediction clearly shows that correlations remain to be greater than 0.5 at 25 lead day and especially higher in summer at longer lead, quite comparable to the prediction skill of the other models.

## 6.3 Forecast skill at seasonal time scales

(anomaly correlation, rms, composites) - MAKE SURE FAIR COMP TO OLD SYSTEM

### 6.3.1 Skill of Global SST, Nino 3.4

ACC computation is based on the 4 hindcasts from 1982 through 2010 started on the same dates for either seasonal forecast system.

Rank histogram is a tool to assess the consistency of the forecast system, to check whether the observations statistically belong to the distribution of the forecast ensembles. Given the small number of forecasts per month, we consider seasonal samples, i.e. we combine 3 months of 4 lagged ensemble members, initialized on the same dates in both forecast systems (S2S\_1 and S2S\_2-1) during the same month to a total of 105 forecasts for DJF, MAM, JJA and SON seasons. In an ideal situation, when the distributions of observations and the forecasts coincide, the rank histogram would be close to a uniform, flat shape. A skewed, "L" shape, of the rank histogram is indicative of a biased forecast ensemble, and a "U" shape is telling that observations tend to fall outside the ensemble envelope, i.e. the forecast ensemble does not have enough spread. Overall across the equatorial Pacific ocean neither system has sufficient spread, measured by the mean deviation from the ideal uniform histogram (marked by the red horizontal line). Larger values of this measure mean worse ensemble spread. The difference between the S2S\_1 and S2S\_2-1 is most dramatic in DJF forecasts (shown in figure 27) in the equatorial Eastern Pacific. In Nino1+2 region the difference between the two systems is remarkable: S2S\_1-0 is biased warm at all leads (1 and 6 are shown here) in all seasons except JJA (not shown here), while the histogram of the S2S\_2-1 ensemble appears much closer to the desired uniform shape, especially at lead 6 (initialized in JJA), with the mean deviation from the uniform is only 0.8. Rank histograms show both systems biased warm in Nino 3.4 regions at lead 1 (initialized in NDJ), but by lead 6 (initialized in JJA) S2S\_2-1 warm bias is reduced, and the ensemble is slightly biased cold.

### 6.3.2 Skill of T2m and Precip

### 6.3.3 Teleconnections and Low Frequency Mode Prediction

here we can look at 1) how well we reproduce these modes, 2) how well we can forecast them (say by looking at some index), and also 3) how well we reproduce their impacts on say T2m and precipitation - by compositing on those indices)

We try to capture the major teleconnection patterns for boreal winter using the 250mb geopotential height (1981-2016) by applying the Rotated Empirical Orthogonal Function (REOF) analysis technique. We first capture the major teleconnection patterns from the MERRA-2 data as a reference. As shown on the right panel in Figure 30, the North Atlantic Oscillation (NAO), Northern Annular Mode/Arctic Oscillation (NAM/AO), and the Pacific North American (PNA) patterns are identified as the first leading teleconnections over the Northern Hemisphere. The same calculation is then applied to the GEOS-S2S\_2.1 hindcast data (one month lead) to assess the capability of the GEOS-S2S\_2.1 for producing those teleconnection patterns. Comparison of the teleconnections indicates that the GEOS-S2S\_2.1 (left panel) successfully captures the spatial structure of the major teleconnections over the Northern Hemisphere. Geographical locations of the positive/negative anomalies seen in the MERRA-2 are quite realistically reproduced in the GEOS-S2S\_2.1 hindcast, though some underestimation of the observed magnitude of the anomalies is found.

We next assess how reliably the GEOS-S2S\_2.1 can predict the phase/intensity of the leading teleconnections in winter. Time series in Figure 31 shows the interannual variation of the January/February averaged teleconnection indices (initialized on Dec. 27) computed from the GEOS-S2S\_2.1 (blue), the old forecasting model (red), and the MERRA-2 (black), respectively. The teleconnection indices are computed by projection of the anomalous 250mb geopotential height over the Northern Hemisphere onto the spatial REOFs of the teleconnections. Comparison in the indices demonstrates that the GEOS-S2S\_2.1 has improved the forecast skill by achieving anomaly correlations greater than 0.5 for all three teleconnections. A little decrease in correlation is found, however, when looking at December/January averaged teleconnections (initialized on Nov. 27). But they are still in an encouraging skill level, with correlations greater than 0.4 (Figure not shown).

#### 6.3.4 TC activity

Predictive skill of seasonal tropical cyclone (TC) activity from the GEOS-S2S\_2.1 is assessed in terms of the Genesis Potential Index (GPI) [Emanuel and Nolan, 2004]. The GPI is generally larger over the period, when the TC activity (e.g., counts and intensity) is stronger than usual, while the GPI tends to be smaller during the weak TC season. We compute the GPI over the North Atlantic and the Western Pacific region, respectively, from the GEOS-S2S\_2.1 hindcast data and then compare the interannual variation of the GPIs with that computed from the MERRA-2. Time series over the period 1982-2016 in Figure 32 show the GPI each year averaged from June through September (initialized on May 31). We adequately assess, based on this figure, the ability of the GEOS-S2S\_2.1 in anticipating the TC activity up to the next four months at the beginning of the TC season. It is clear that both GEOS-S2S\_2.1 and old forecasting models are capable of predicting reliably the anomalous (above or below average) TC activity for the first four months (JJAS). Comparison in correlations indicates relatively better performance by the GEOS-S2S\_2.1. Correlations are 0.55 for the North Atlantic and even up to 0.82 for the Western Pacific basin, while those two values are 0.52 and 0.68, respectively, from the old forecasting system.

#### 6.3.5 Cryosphere

The presence and character of sea ice critically alters the local energy and moisture exchange between the ocean and atmosphere, affecting the local Arctic and Antarctic climate. In the Arctic, the accelerated reduction of sea ice cover in recent years is also associated with a regional amplification in near-surface air temperatures [Screen and Simmonds, 2010; Serreze and Barry, 2011]. These effects may also influence the larger-scale general circulation [Alexander et al., 2004; Deser et al., 2010; Screen et al., 2018]. Appropriate treatment of sea ice characteristics in seasonal forecasting models may then influence Northern Hemisphere predictive skill [Jung et al., 2014]; however, there is uncertainty in the causal relationship between Arctic sea ice conditions and midlatitude weather variability [Overland et al., 2015], in part due to the limited the atmospheric response to sea ice variability in climate models

824 [Screen *et al.*, 2018]. Nevertheless, local improvements in sea ice forecasts provide useful  
825 information for Arctic stakeholders [Ban *et al.*, 2016].

826 The GEOS S2S Version 1 forecasting system demonstrated reasonable predictive skill  
827 of hemispheric sea ice cover, with June forecasts explaining approximately 50 percent of the  
828 observed variance in the September Arctic ice extent (Figure 38a). Forecasts of the mini-  
829 mum sea ice extent also fared well when compared with other dynamical models in the Sea  
830 Ice Outlook [Borovikov *et al.*, 2017]. In producing GEOS-S2S Version 2, a key goal was to  
831 assess an upper limit on predictive skill with the current model configuration. To this end,  
832 forecasts for the retrospective period were initialized with ice thickness values from a vali-  
833 dated modeling system (GIOMAS: Global Ice-Ocean Modeling and Assimilation System;  
834 Schweiger *et al.* [2011]). The use of GIOMAS sea ice thicknesses resulted in substantial im-  
835 provement in forecast skill at longer lead time. In the Arctic, the system also benefitted from  
836 the use of the GEOS Forward Processing for Instrument Teams analysis (FP-IT), a near-real  
837 time derivative of the MERRA-2 reanalysis. The FP-IT incorporates a seasonally-varying  
838 sea ice albedo for improved air temperatures in the atmospheric forcing [Gelaro *et al.*, 2017].  
839 The use of GIOMAS and FP-IT atmospheric forcing effectively eliminated a large spring-  
840 time negative sea ice extent bias found in earlier versions of the seasonal prediction system  
841 (Figure 33a).

842 A credible initial ice thickness field has been widely demonstrated to improve the sea-  
843 sonal forecast skill for sea ice extent (e.g., Blanchard-Wrigglesworth *et al.* [2017]; Chevallier  
844 and Salas-MÀllia [2011]; Day *et al.* [2014]). Retrospective forecasts of the GEOS-S2S Ver-  
845 sion 2 system using GIOMAS explain between 70 and 82 percent of the sea ice variability, a  
846 substantial improvement over the previous system (Figure 33). However, much of the skill is  
847 derived from predicting the long-term decreasing trend in sea ice extent. The model's skill  
848 is substantially reduced when the forecast extent is linearly detrended (after Bushuk *et al.*  
849 [2012]). Over the retrospective period, the GEOS S2S Version 2 July forecast explains ap-  
850 proximately 30 percent of the detrended sea ice extent variability. This reduction in the de-  
851 trended forecast skill arises from difficulties in predicting anomalously high or low sea ice  
852 extents (i.e., the anomalous summer extents of 1996, 2007, 2012, etc.), and is commonly  
853 found in dynamical sea ice forecasting models (e.g., Hamilton and Stroeve [2016]). The re-  
854 sults nevertheless highlight the importance of deriving an accurate, historical record of ice  
855 thickness and methods for incorporating near real-time ice thickness observations in future  
856 seasonal forecasting systems.

857 Changes in glacier and ice sheet surface mass balance (SMB: here, the net of precipita-  
858 tion minus evaporation/sublimation and runoff) may alter the climate on seasonal timescales  
859 via local changes to surface energy budget characteristics (i.e. ice surface albedo; [Box *et al.*,  
860 2012] and through the selective discharge of freshwater, which may impact local fjord circu-  
861 lation as well as ocean stratification [Mortensen *et al.*, 2013; Sciascia *et al.*, 2013]. Change  
862 in runoff may also impact the pattern and timing of ocean nutrient delivery and dependent  
863 phytoplankton production, particularly in the Northern Hemisphere [Bhatia *et al.*, 2013;  
864 Sommaruga, 2015]. Therefore, the appropriate representation of glacier and ice sheet SMB  
865 processes is an important step in improving the complexity of seasonal prediction systems  
866 and may provide valuable information to a range of stake holders.

867 The GEOS S2S Version 2 system incorporates the same snow and ice scheme as used  
868 in MERRA-2 [Cullather *et al.*, 2014]. Snow cover is explicitly represented with a modified  
869 version of the Stieglitz snow model [Lynch-Stieglitz, 1994; Stieglitz *et al.*, 2001], which caps  
870 snow depth at 15m and snow density at  $500 \text{ kg m}^{-3}$ . Snow cover is permitted to be frac-  
871 tional. The underlying ice column is composed of 15 layers, for an adequate representation  
872 of surface heat conduction, with a lower boundary condition of zero heat flux. Meltwater  
873 runoff may occur both from the snow column and directly from the ice surface. This pro-  
874 duces a reasonable representation of SMB for the Greenland Ice Sheet (GrIS) when com-  
875 pared to both in situ measurements and high-resolution regional climate models [Cullather  
876 *et al.*, 2014], although the reduced spatial resolution may limit the ability to appropriately

877 represent the surface melt spatial extent and gradients within the ablation zone. Nevertheless,  
878 the results compare well with localized observations [*Smith et al.*, 2017].

879 The current forecasting system reasonably reproduces the spatial pattern of mean SMB  
880 during the retrospective forecast period at 1-month lead times (1981-2016; Figure 34). Re-  
881 gions of high snow accumulation in southeastern GrIS are clearly present; however, accumu-  
882 lation is a moderately under-predicted. This occurs primarily due to an under prediction of  
883 snowfall during winter months and April. In addition, SMB within the ablation zones of the  
884 western GrIS, Iceland, and the northeastern Canadian Arctic are generally over predicted at  
885 1-month lead times, reducing their spatial extent. For the GrIS and nearby areas, this over-  
886 prediction of SMB is primarily driven by an under-prediction of summertime ice sheet runoff  
887 during the latter part of the retrospective forecast period (Figure 34c). The conditions associ-  
888 ated with the more recent retrospective forecasts are generally associated with a strong nega-  
889 tive NAO and a strong positive EA during summer months, leading to high pressure blocking  
890 and warmer air temperatures, particularly over the western GrIS [*Lim et al.*, 2016], which do  
891 not develop as strongly as observed in the GEOS S2S Version 2 system. This decline in SMB  
892 forecast skill and the under-prediction of ice surface runoff during years and with a strong  
893 negative NAO also corresponds to an overestimate in the predicted summertime sea ice cover  
894 at leads of 3-4 months. Localized feedbacks between sea ice extent and ice sheet runoff (e.g.,  
895 *Liu et al.* [2016]) and initial conditions and ice sheet surface albedo feedbacks may also play  
896 a role in summertime SMB forecasting [*Box et al.*, 2012; *Tedesco et al.*, 2013]. However, in  
897 forecasting seasonal changes in GrIS surface conditions, the need to accurately predict the  
898 phase of the summertime NAO is clearly a limiting factor.

899 Aside from the trend toward reduced skill in the retrospective period, May forecasts are  
900 found to predict approximately 66 percent of the total variance of the JJA (lead times of 1-3  
901 months) SMB relative to MERRA-2. This reduction suggests that much of the skill in pre-  
902 dicting summer SMB arises from the ability to predict the recent trend towards enhanced ice  
903 sheet melt and runoff [*Khan et al.*, 2015], and not necessarily in predicting the SMB interan-  
904 nual variability.

#### 914 6.4 Results of Aerosol Forecast

915 We used the Modern-Era Retrospective Analysis for Research and Applications, ver-  
916 sion 2 (MERRA-2, *Gelaro et al.* [2017]) aerosol optical depth (AOD) at 550nm channel re-  
917 analysis *Randles et al.* [2017] to evaluate the GEOS-5 sub-seasonal to seasonal (S2S) aerosol  
918 hindcast simulations. Our analysis focused on the trimesters December, January, and Febru-  
919 ary (DJF), and July, August, and September (JAS) from 2000 to 2015.

920 The MERRA-2 aerosol reanalysis applies the Goddard Aerosol Assimilation Sys-  
921 tem (GAAS, *Buchard et al.* [2015]; ?). The AOD observing system used in MERRA-2 in-  
922 cludes ground-based Aerosol Robotic Network (AERONET) direct measurements of AOD  
923 ?, AOD from the Multiangle Imaging SpectroRadiometer (MISR) over bright surfaces ?, and  
924 bias-corrected near-real-time (NNR) data from the Moderate Resolution Imaging Spectro-  
925 radiometer (MODIS) from Terra and Aqua, and from the Advanced Very High Resolution  
926 Radiometer (AVHRR) instruments. *Randles et al.* [2017] describes in details the data and  
927 its spatial and temporal coverage. The aerosol emissions fields used for the GEOS-5-S2S  
928 hindcast simulations were the same as the applied for the MERRA-2. Emissions of dust and  
929 sea salt are wind driven ??, respectively. Sea salt emission is also modulated with a sea sur-  
930 face temperature (SST)-derived correction following ?. Biomass burning emissions have  
931 daily variability and are from the Quick Fire Emissions Dataset (QFED) version 2.4-r6 ?.  
932 MERRA-2 includes bias corrected aerosol data assimilation and the GEOS5-S2S aerosol  
933 hindcast data analysis also includes the bias correction relative to MERRA-2. Therefore,  
934 comparing them, we are evaluating the model performance to predict the aerosol distribution  
935 as result of transport and removal processes.

936 Figure 35 shows scatter plots of the globally and monthly averaged AOD from the  
 937 GEOS5-S2S ensemble mean relative to the MERRA-2 correspondents, from 2000 to 2015.  
 938 However, climate model has a better performance during the Austral winter ( $R=0.81$ ,  $R^2=0.65$ ,  
 939  $SE=0.006$  and  $bias=-0.001$ ) compared to boreal winter ( $R=0.73$ ,  $R^2=0.54$ ,  $SE=0.005$  and  
 940  $bias=0.015$ ).

941 In general, the GEOS5-S2S aerosol global mean and seasonal spatial distributions are  
 942 in agreement with MERRA-2, capturing the main patterns of the biomass burning aerosols  
 943 over South America, Africa austral and the South Atlantic Ocean, the position of the dust  
 944 plume coming from the Sahara desert, and the Asian pollution plume (Figure 36 panels A-  
 945 B and D-E). The global mean AOD from GEOS5-S2S for the JAS and DJF trimesters are  
 946 0.16 and 0.12, respectively; while the correspondent MERRA-2 values are 0.17 and 0.14.  
 947 However, we observed biases over a few specific regions (Figure 36, panels C and F). During  
 948 the Austral winter (JAS) GEOS5-S2S overestimates the AOD on the southwestern coast of  
 949 Africa, India, and Boreal forest in North America and Asia, and underestimates over South  
 950 America and southeast Asian, associated to biomass burning emissions. It is noticeable (not  
 951 shown) that the AOD biases correlate well with the precipitation biases in South America  
 952 and Africa. Therefore, the climate model overestimation and underestimation over Africa  
 953 and South America, respectively, is likely related to the model ability to predict precipita-  
 954 tion accurately, and therefore the wet removal processes over these regions. For the same  
 955 period, GEOS5-S2S also overestimates the AOD on the north of Africa and the Middle East,  
 956 related to dust emissions. The positive AOD biases associated with dust aerosols are related  
 957 with stronger winds simulated by the GEOS5-S2S compared to the meteorological reanaly-  
 958 sis. A similar feature and bias have been previously reported for the GEOS5 model results  
 959 ????. During the Boreal winter (DJF), the climate model predicted an intense aerosol load-  
 960 ing all over the Arctic region, and over Central Africa, associated with boreal fires. On the  
 961 other side, the GEOS5-S2S prediction underestimated the AOD over India, northern South  
 962 America, and eastern Asia. The climate prediction of sea-salt aerosols over oceanic regions  
 963 are typically underestimated both over the Southern and Northern Hemispheres during the  
 964 Austral and Boreal winter. This underestimation is likely related to the prediction of me-  
 965 teorological factors influencing sea-salt emissions, such as wind speed at 10m and the sea  
 966 surface temperature (SST). However, the possible effects of these influences are yet not well  
 967 understood and therefore will not be discussed here.

## 977 7 Summary and Future Directions

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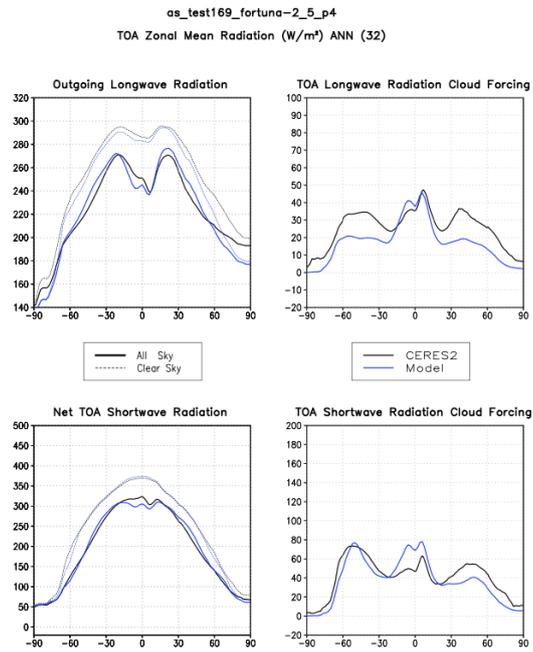
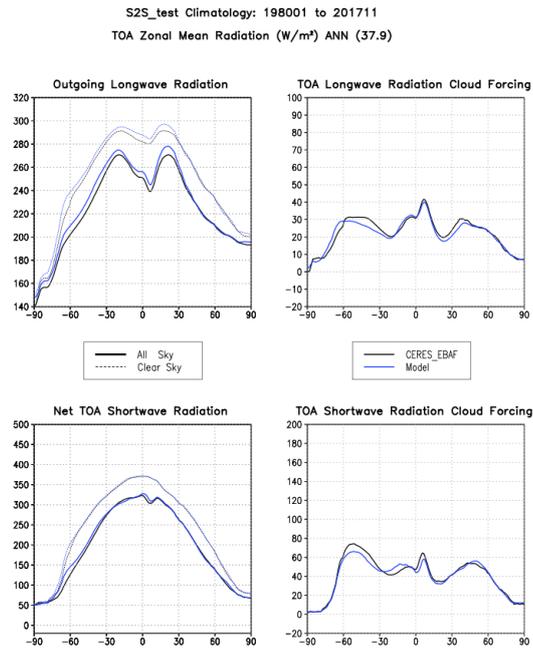


Figure 4.

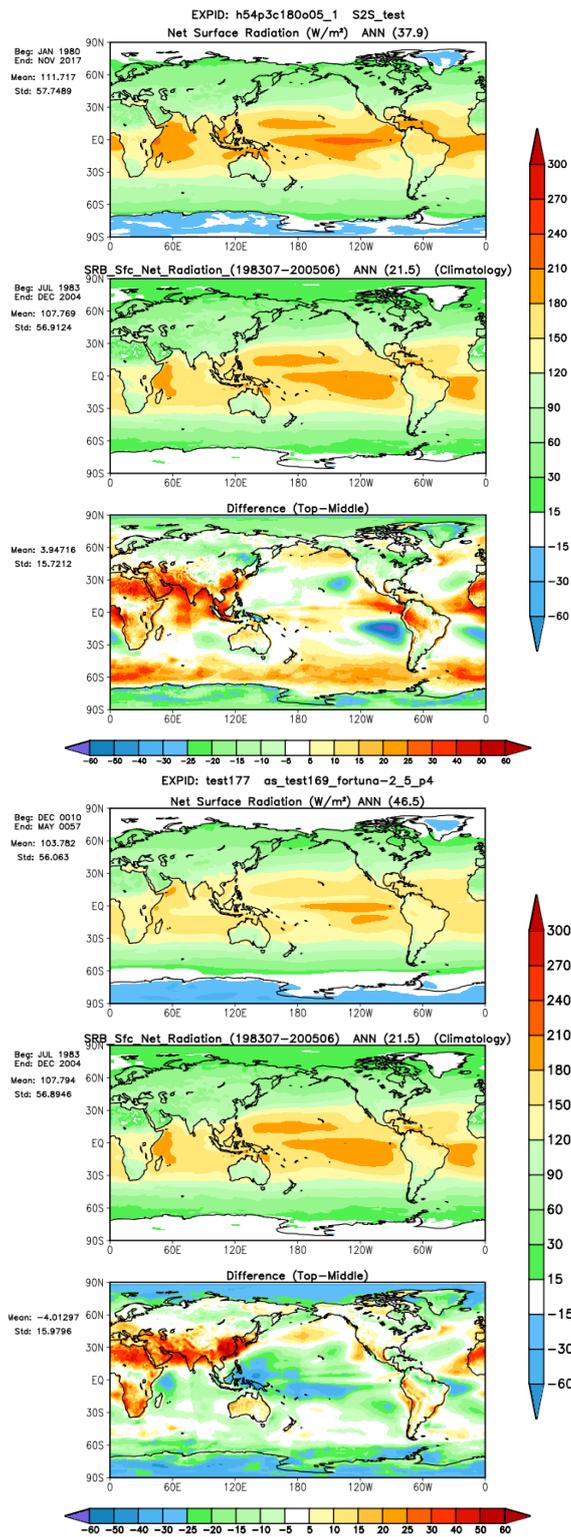


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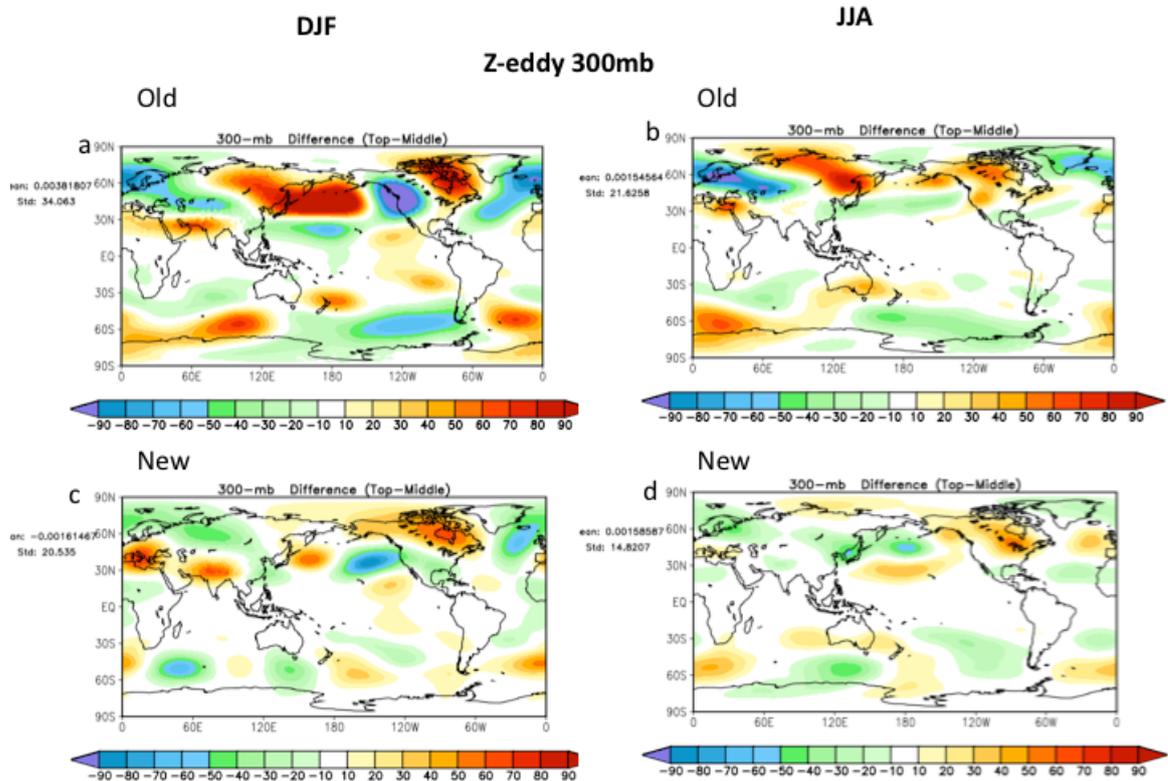


Figure 1

483 **Figure 6.** Seasonal mean Eddy Height difference from MERRA-2 at 300 mb in m. a)December-January-  
 484 February mean for S2S-1\_0, b) June-July-August mean for S2S-1\_0, c) December-January-February mean for  
 485 S2S-2\_1, d) June-July-August mean for S2S-2.



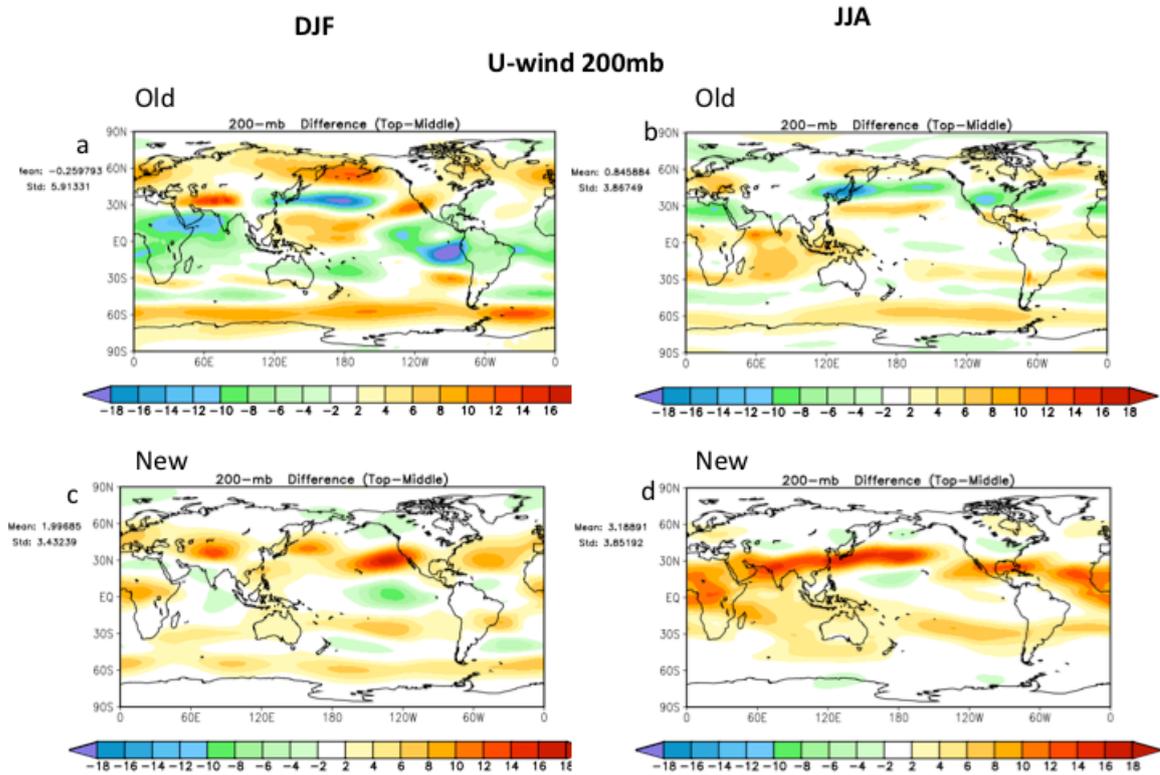


Figure 2

486 **Figure 7.** Seasonal mean Zonal wind difference from MERRA-2 at 200 mb in  $ms^{-1}$ . a) December-January-  
 487 February mean for S2S-1, b) June-July-August mean for S2S-1, c) December-January-February mean for  
 488 S2S-2, d) June-July-August mean for S2S-2.

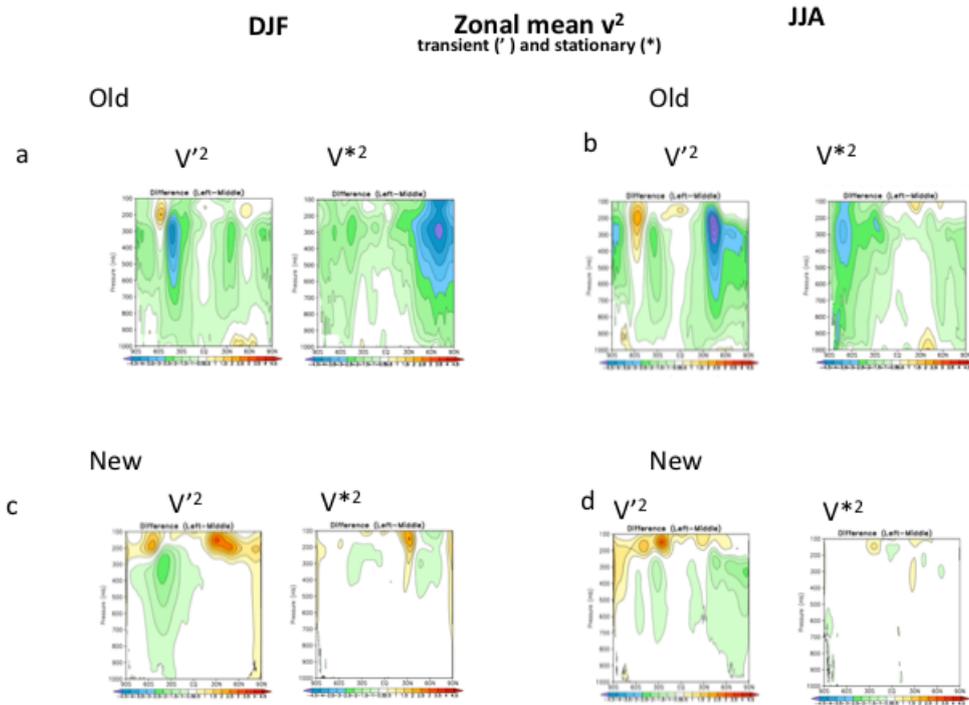


Figure 3

3

489 **Figure 8.** Seasonal mean difference from MERRA-2 of the stationary and transient components of the vari-  
 490 ance of meridional wind in  $m^2s^{-2}$ . a) December-January- February mean for S2S-1\_0, b) June-July-August  
 491 mean for S2S-1\_0, c) December-January-February mean for S2S-2\_1, d) June-July-August mean for S2S-2\_1.

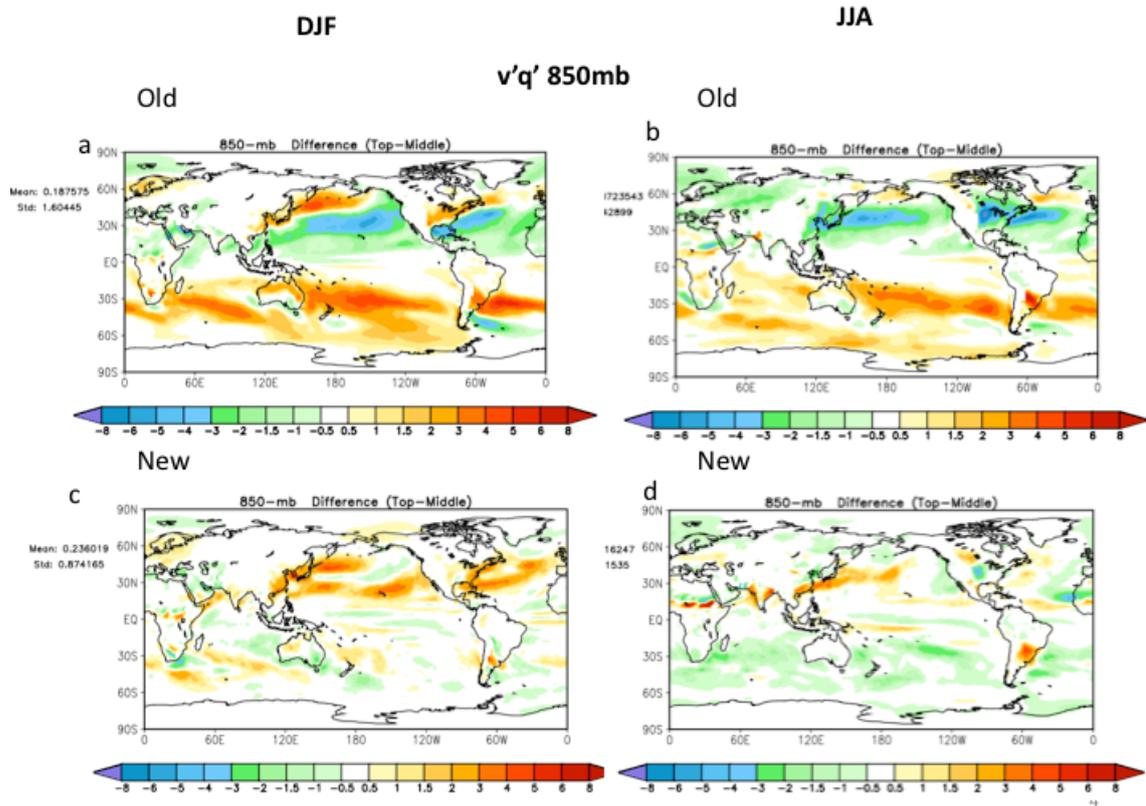
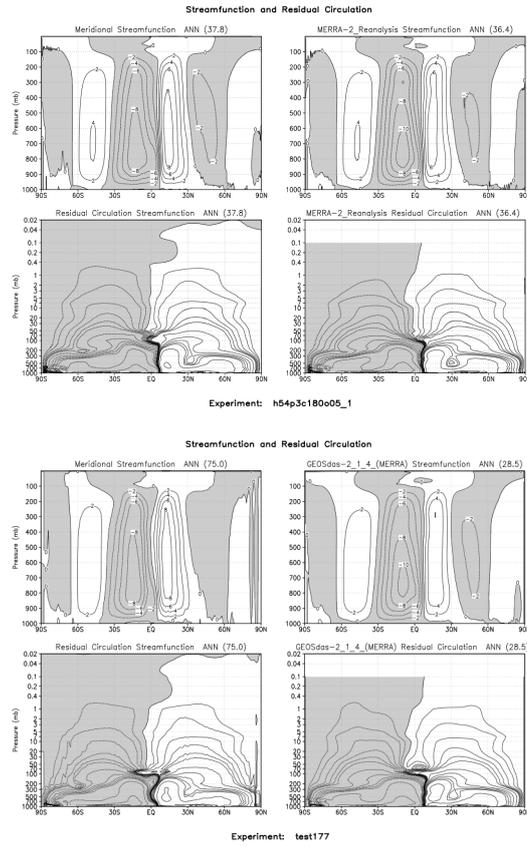


Figure 4

492 **Figure 9.** Seasonal mean difference from MERRA-2 of the transient meridional transport of moisture at  
 493 850 mb in  $gkg^{-1}ms^{-1}$ . a) December-January- February mean for S2S-1\_0, b) June-July-August mean for  
 494 S2S-1\_0, c) December-January-February mean for S2S-2\_1, d) June-July-August mean for S2S-2\_1.



495

**Figure 10.** Mean Meridional Circulation....

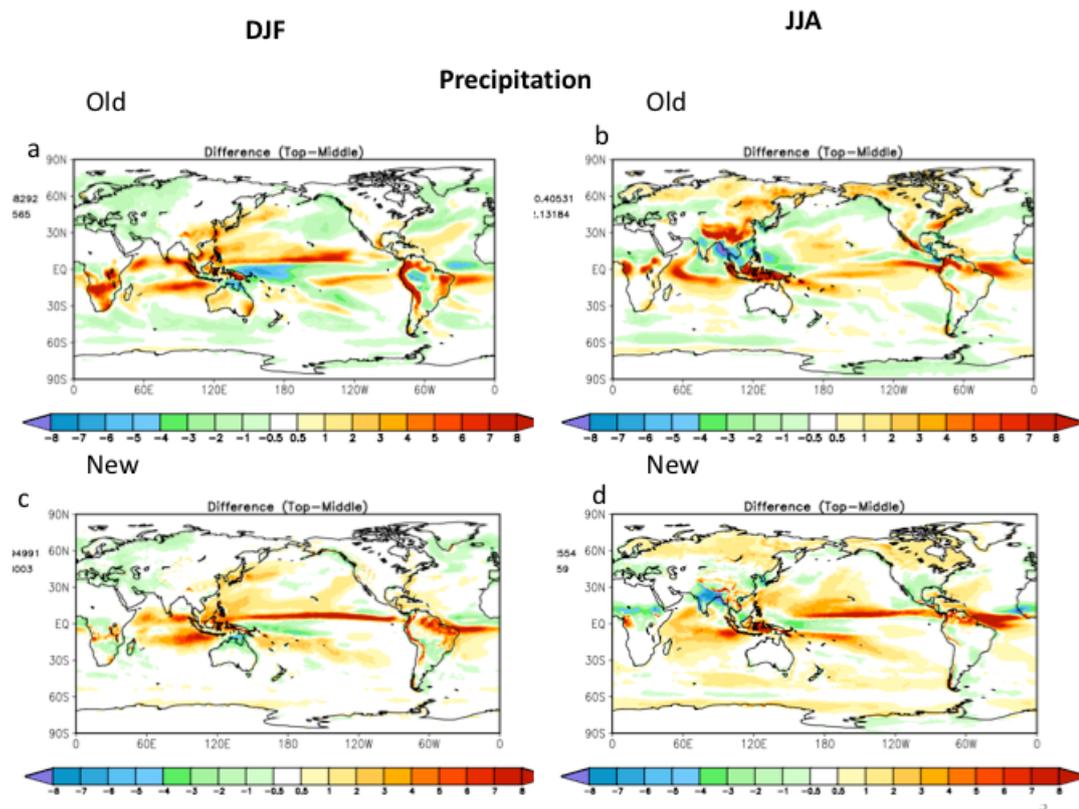


Figure 5

Figure 11.

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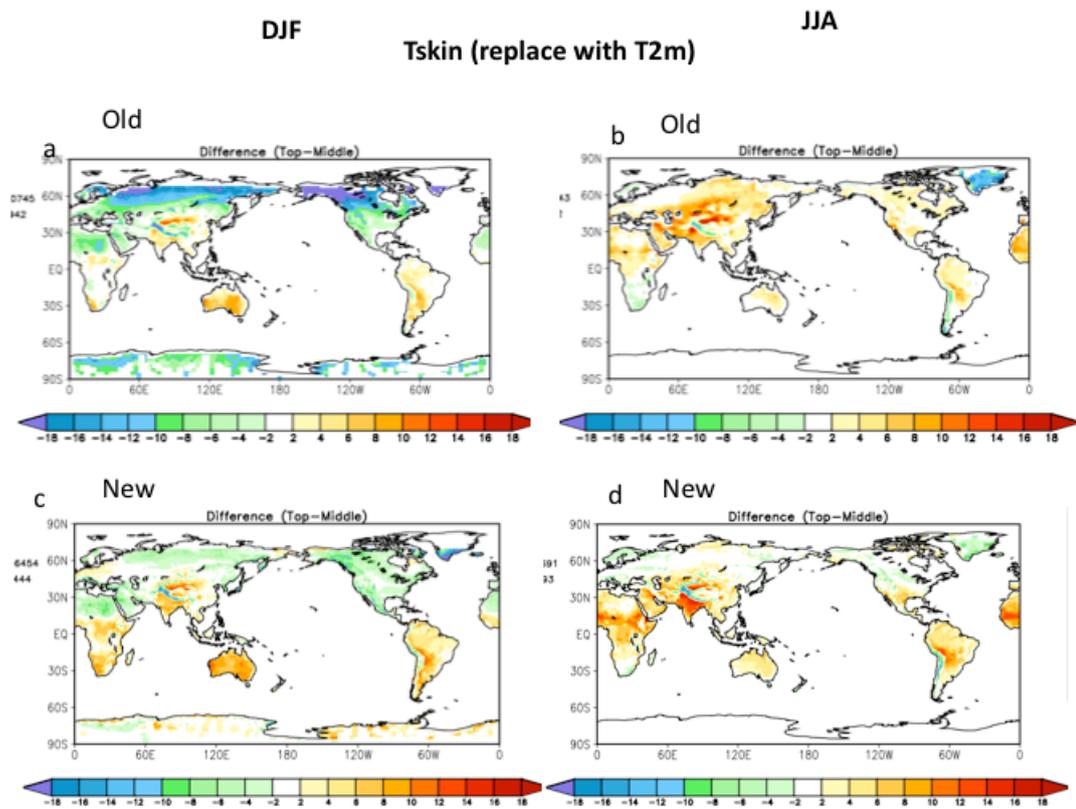


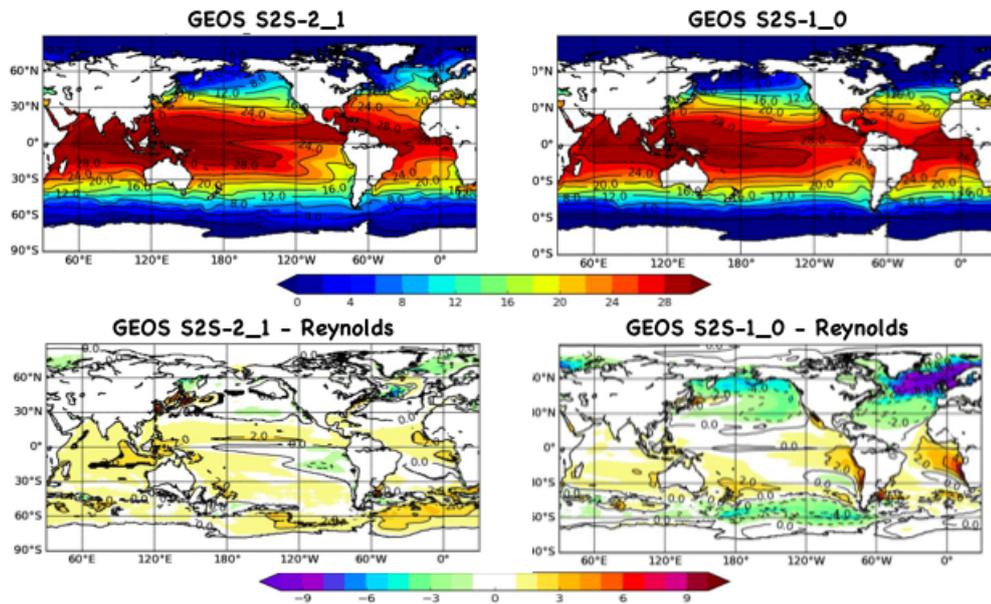
Figure 6

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Figure 12.

National Aeronautics and Space Administration

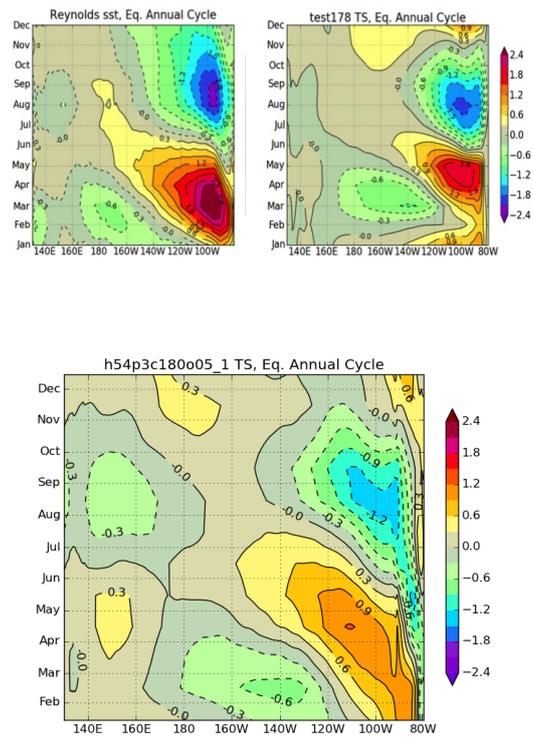
### SST Annual Mean



**GMAO** Global Modeling and Assimilation Office  
gmao.gsfc.nasa.gov

509 **Figure 13.** GEOS S2S-2\_1 and GEOS S2S-2\_0 Sea surface temperature differenced from Reynolds analy-  
510 sis

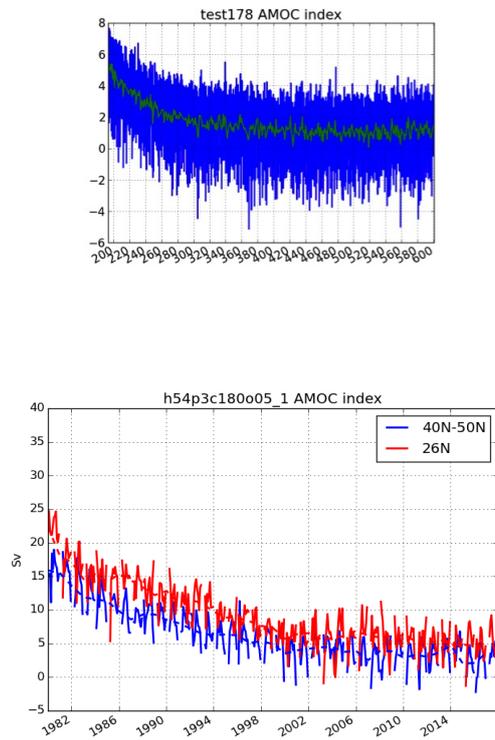
### Equatorial Annual Cycle



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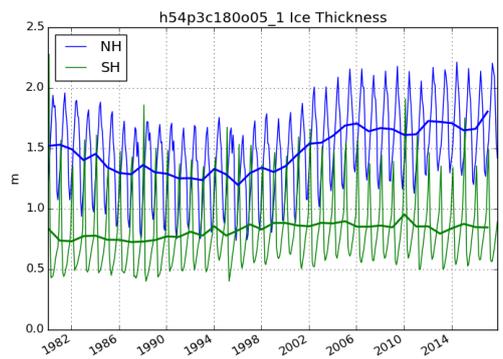
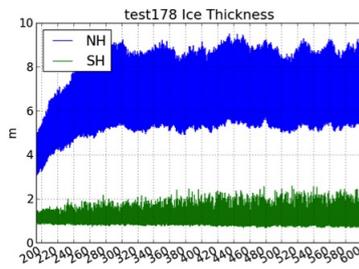
Figure 14.





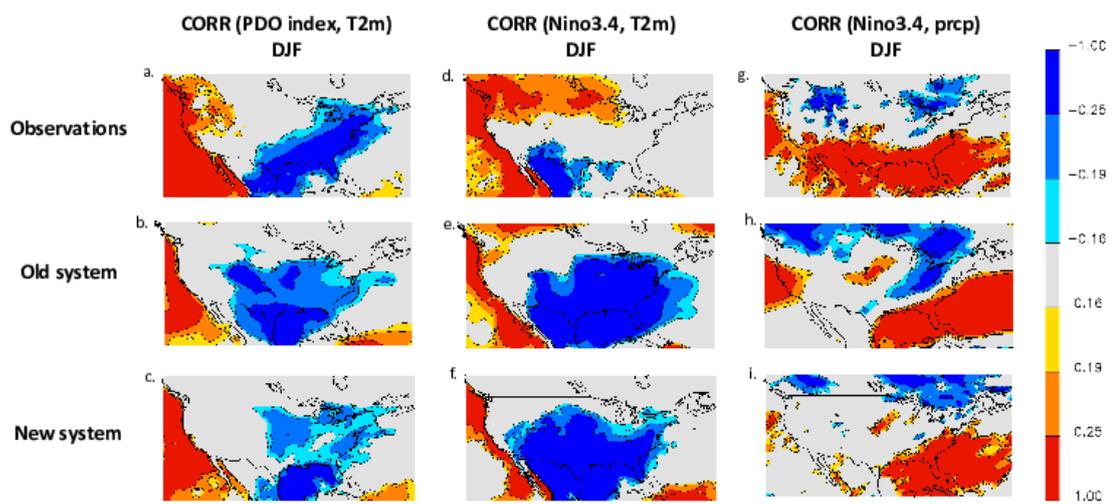
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Figure 15.

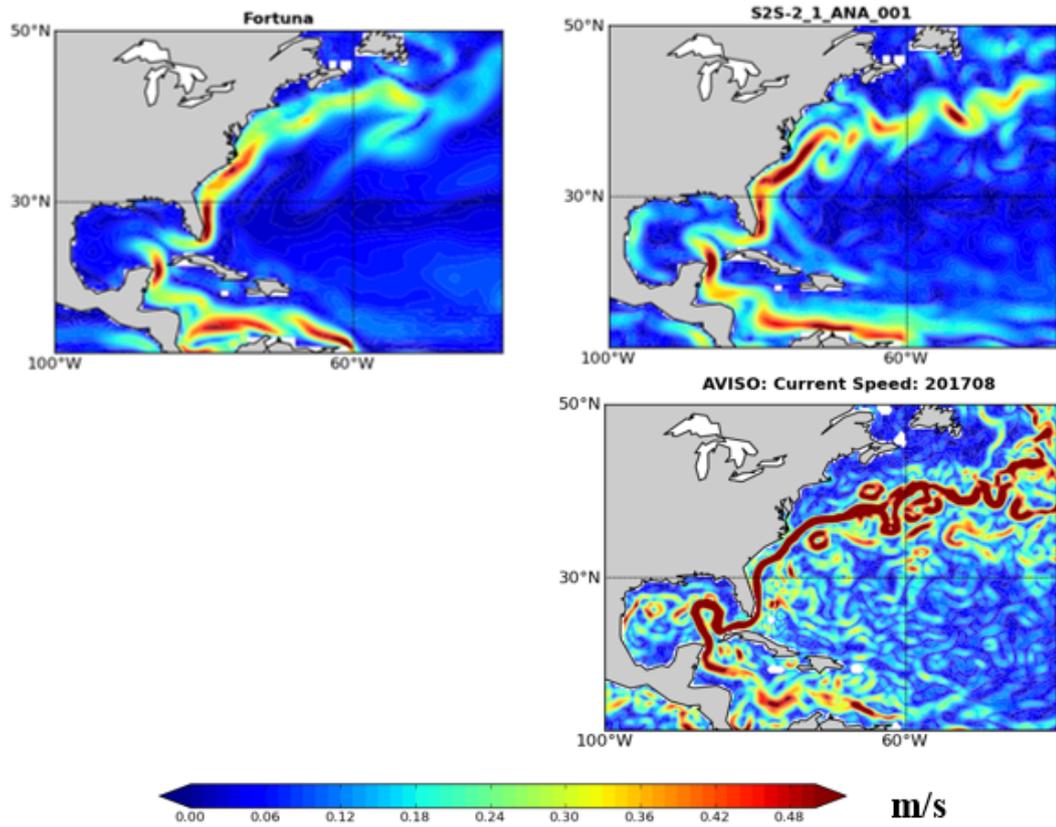


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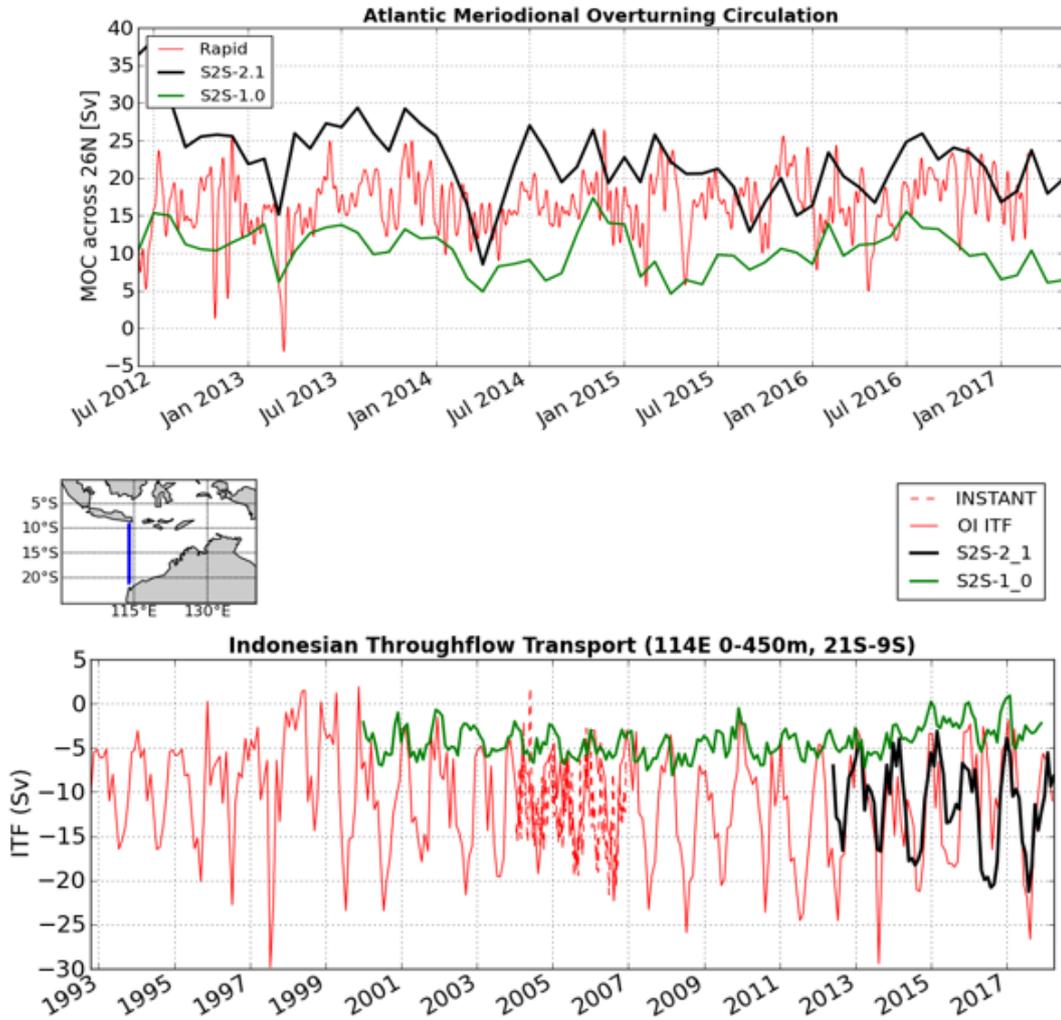
Figure 16.



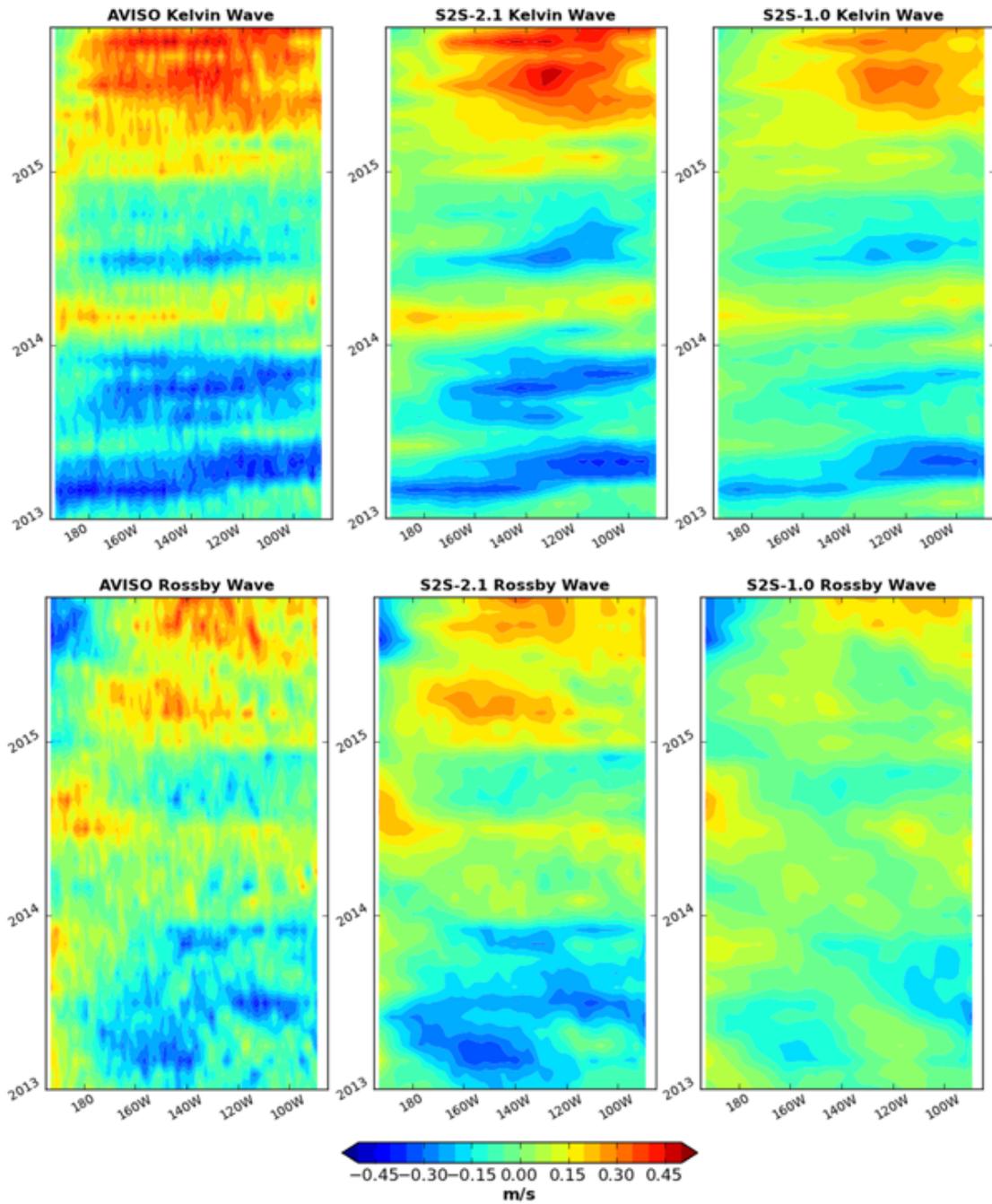
553 **Figure 17.** Schematic of the replay process to apply the ODAS. Horizontal blue (red) arrow indicates the  
 554 ocean forecast (analysis) ocean model execution. Vertical arrows represent observers taken every 6 hours.  
 555 Steps in the process are indicated by green circled numbers and defined in the key.



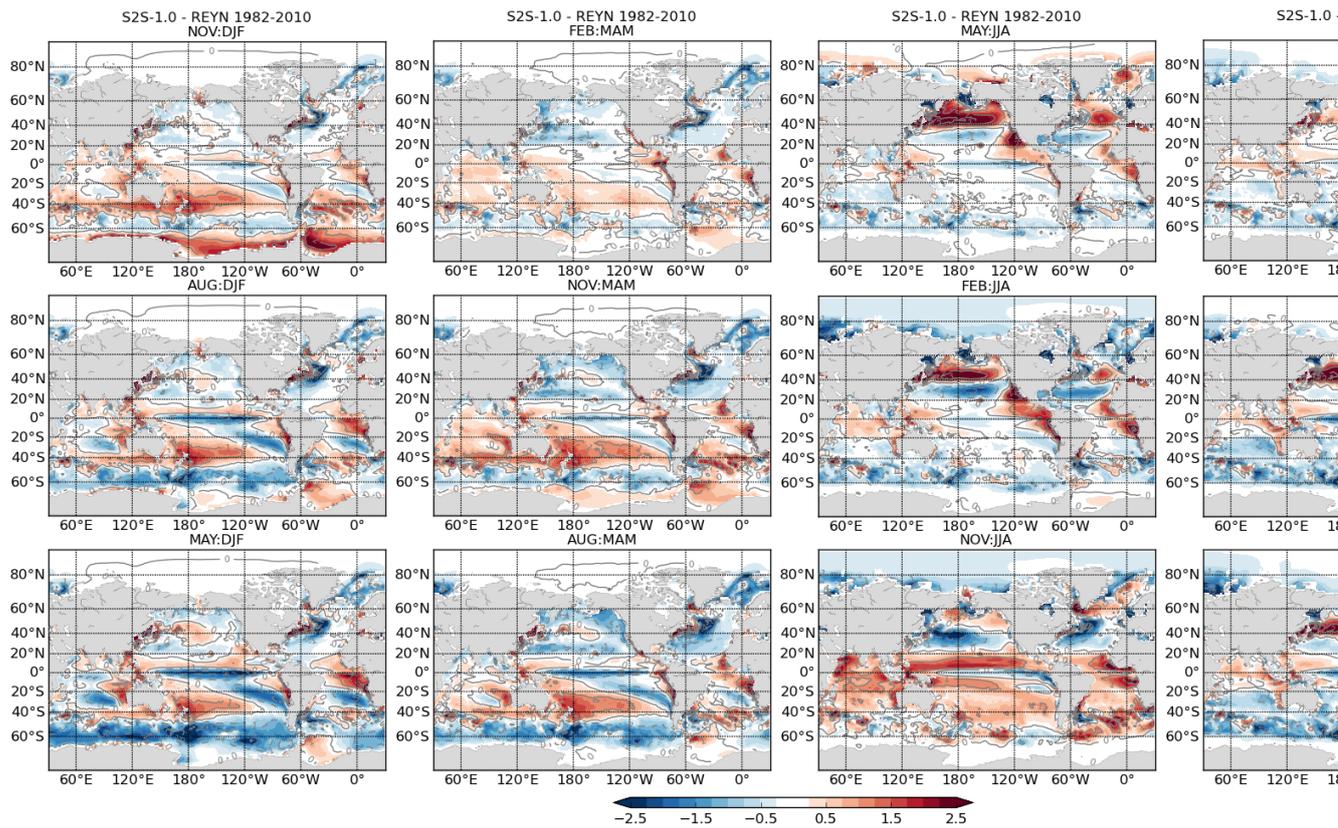
584 **Figure 18.** Current speed for western boundary currents for August 2017. Top left panel is the S2S-v1.0,  
585 top right is for S2S-v2.1, and the bottom right is geostrophic currents from the AVISO multi-satellite product.



618 **Figure 19.** Major global heat conveyor belt indices, top) the Atlantic Meridional Overturning circulation  
 619 (AMOC) is measured by in situ observations of the RAPID array (red) across 26.5oN in the Atlantic. S2S-  
 620 v1.0 (green) and S2S-v2.1 (black) are compared over July 2012 until July 2017. The bottom panel shows  
 621 indices of the Indonesian Throughflow (see inset for location). Geostrophic transport calculated using an  
 622 optimal interpolation (*Carton [1989]*) of all available in situ temperature and salinity observations (solid red)  
 623 compares well with in measurements from INSTANT moorings *Sprintall et al. [2009]* (dashed red). S2S-v1.0  
 624 (green line) clearly underestimates the ITF transport whereas S2S-v2.1 (black line) corresponds well with  
 625 observations.

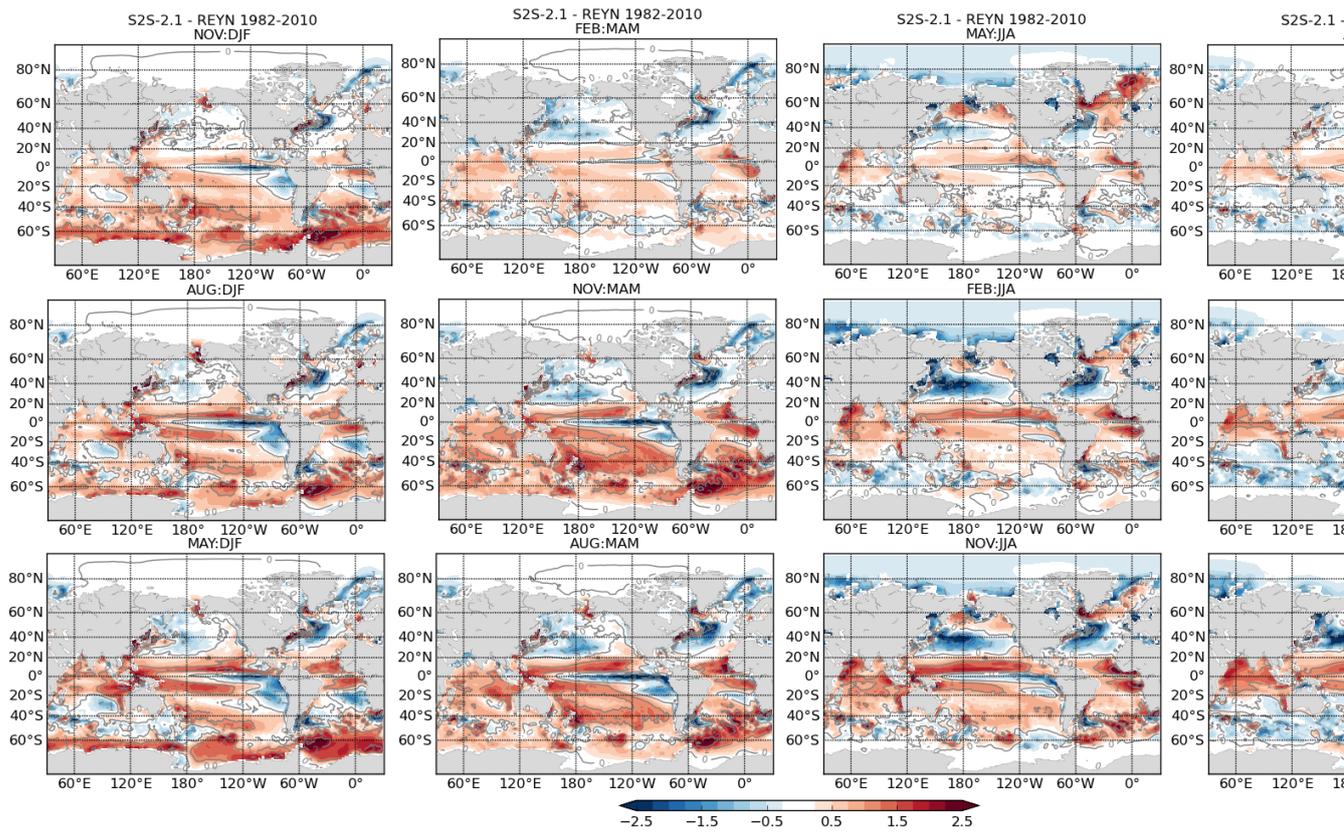


657 **Figure 20.** Longitude versus time distribution of the equatorial (top) Kelvin and (bottom) the first merid-  
 658 ional mode of equatorial Rossby waves through their signature in zonal surface current deduced from the  
 659 observed AVISO multi-satellite altimetry AVISO [2013] (left), S2S-v1.0 (middle) and S2S-v2.1 (right).  
 660 Kelvin waves travel west-to-east and take about 3 months to transit the Pacific and Rossby waves travel from  
 661 east-to-west and take about 8 months.



**Figure 21.** S2S-1.0 seasonal mean SST drift at 1, 3, 6 months leads.

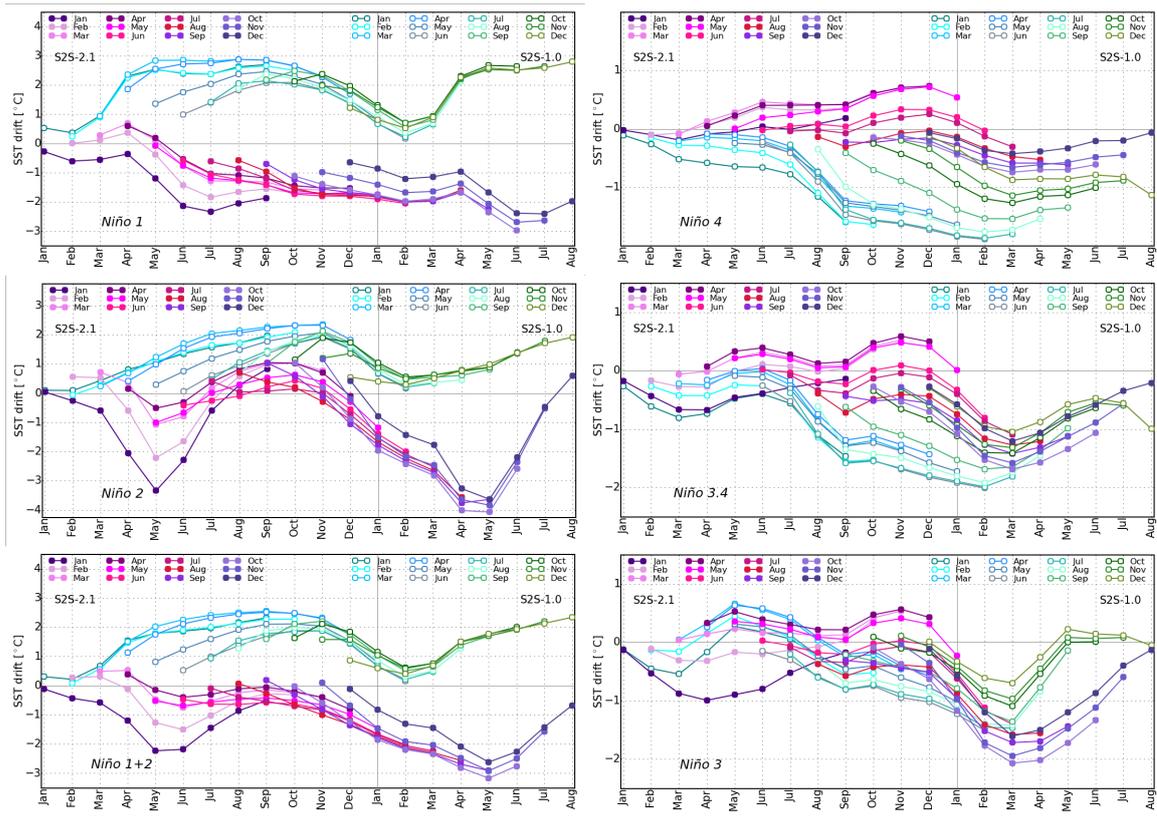
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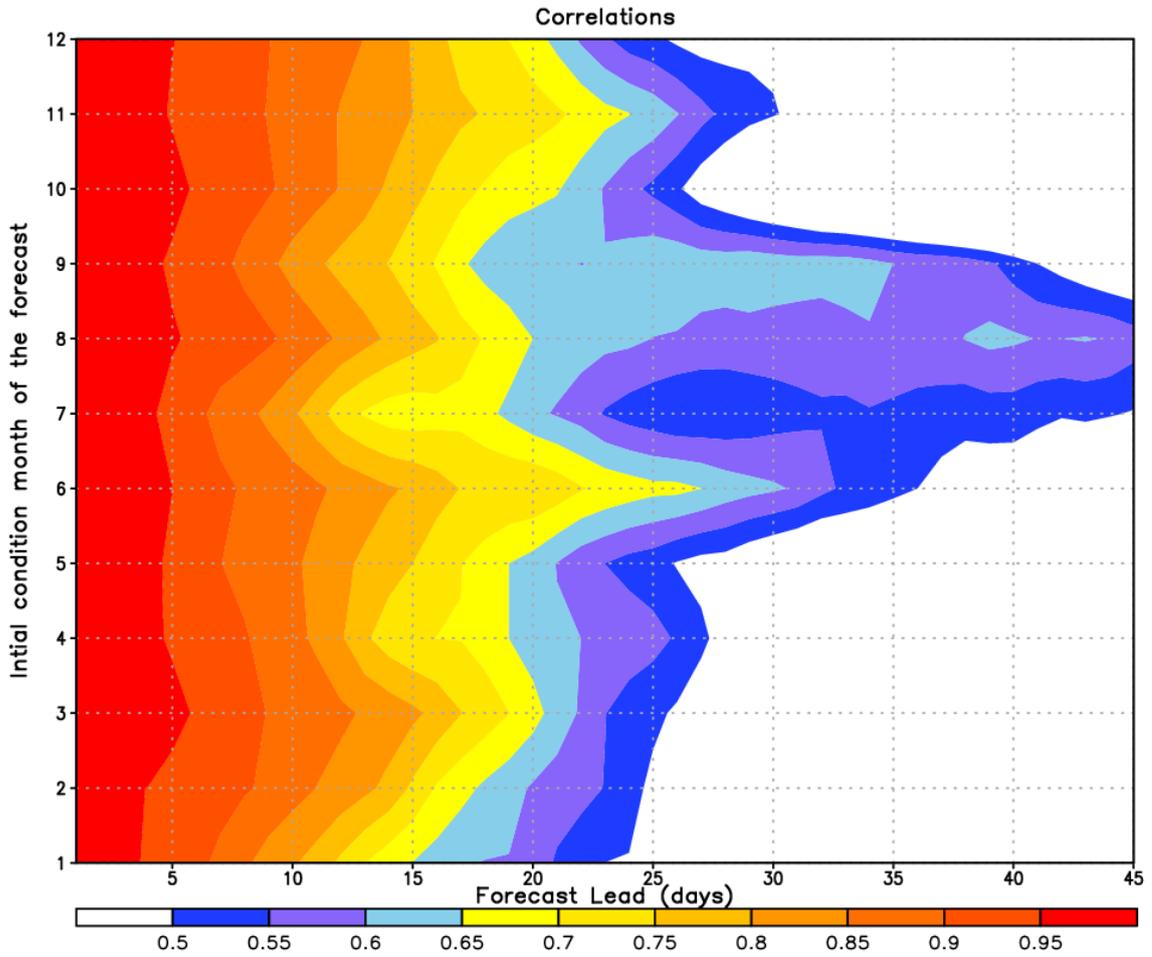
**Figure 22.** S2S-2.1 seasonal mean SST drift at 1, 3, 6 months leads.

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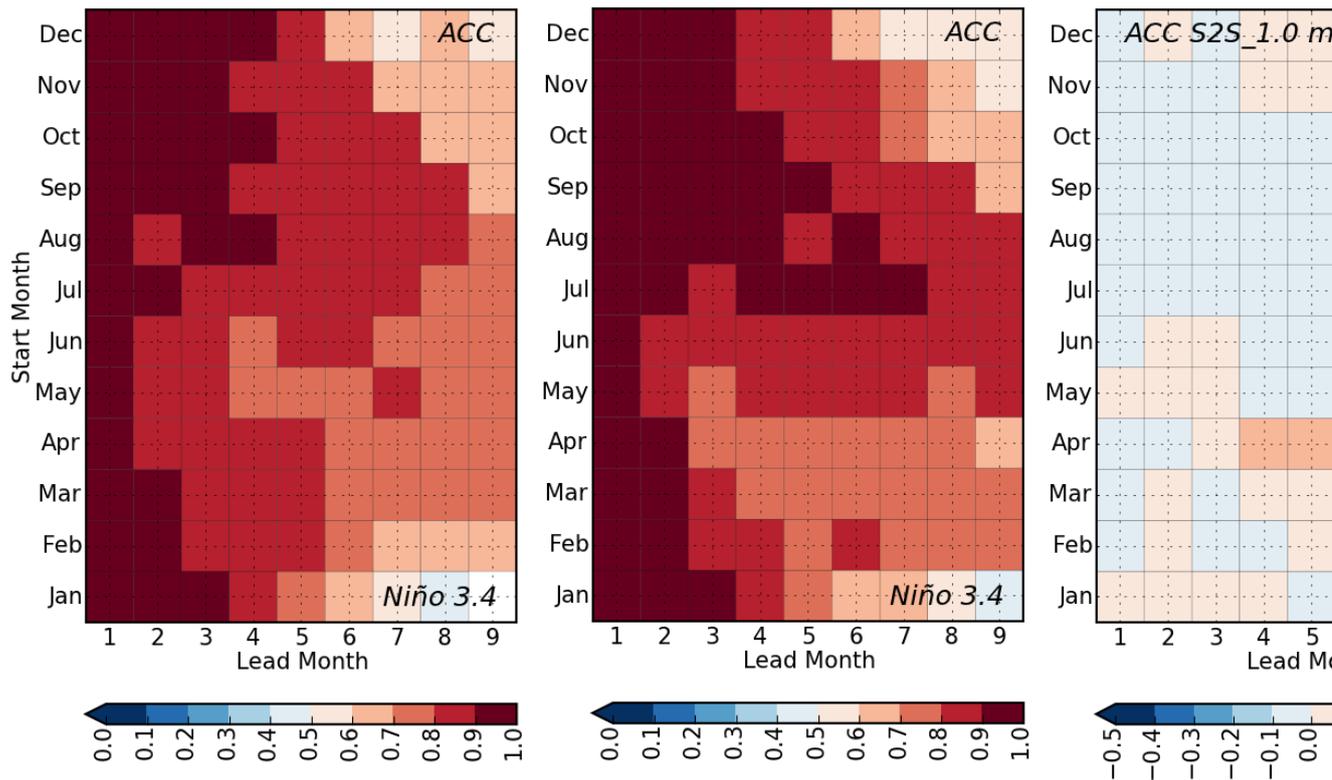




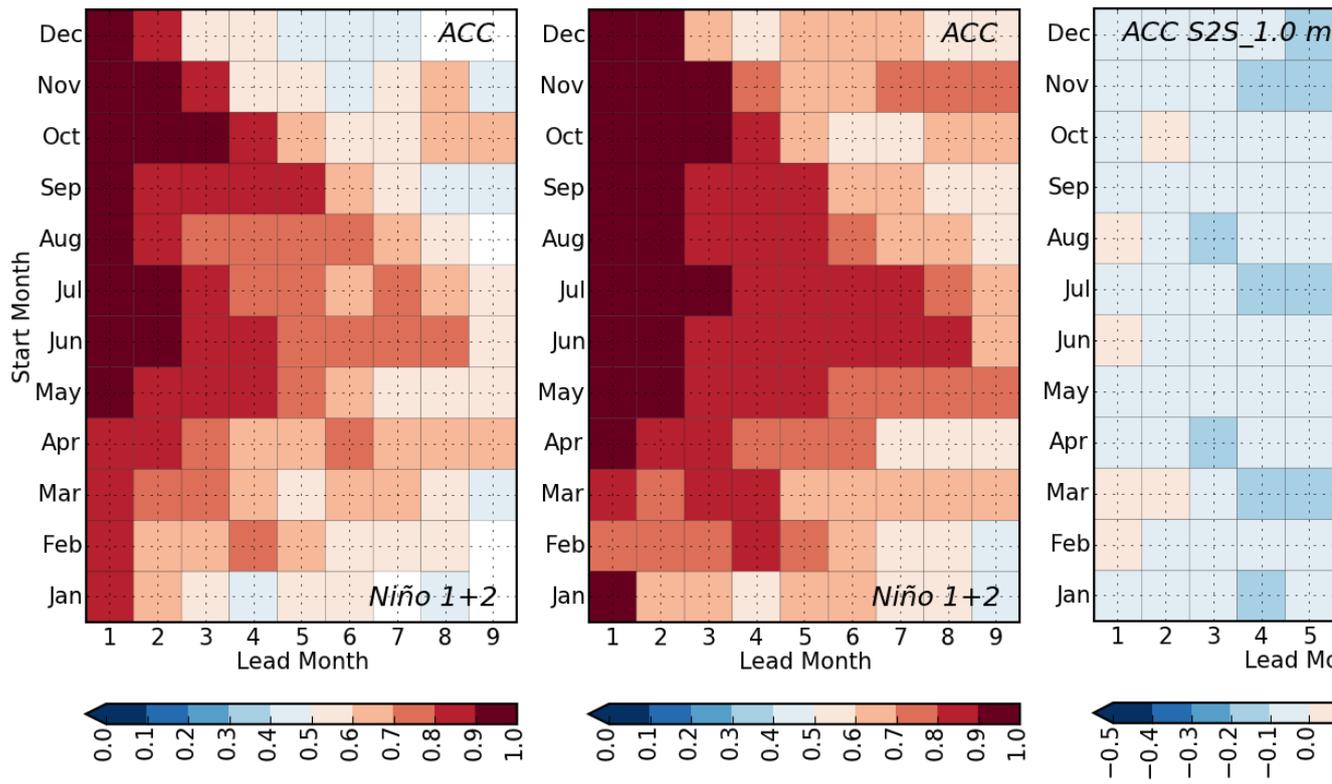
698 **Figure 23.** S2S-1.0 and S2S-2.1 monthly mean drift for ENSO indices with respect to Reynolds. Filled  
 699 circles correspond to S2S-2.1, empty circles to S2S-1.0. The forecasts are color-coded by their initialization  
 700 month with pink/purple colors for S2S\_2.1 and green/blue for S2S\_1.0.



717 **Figure 24.** Prediction skill of the MJO in terms of the bivariate anomaly correlation of the MJO indices.  
 718 They are calculated following [Wheeler and Hendon, 2004] and [Gottschalck et al., 2010]. The retrospective  
 719 forecasts are carried out for the period 1999-2016, with initial dates at every five days forecasting for 45 days.  
 720 Prediction skill is assessed for the 45 day forecast periods, when the observed MJO is present. X-axis denotes  
 721 the forecast lead day while y-axis is the initial condition month of the forecast.

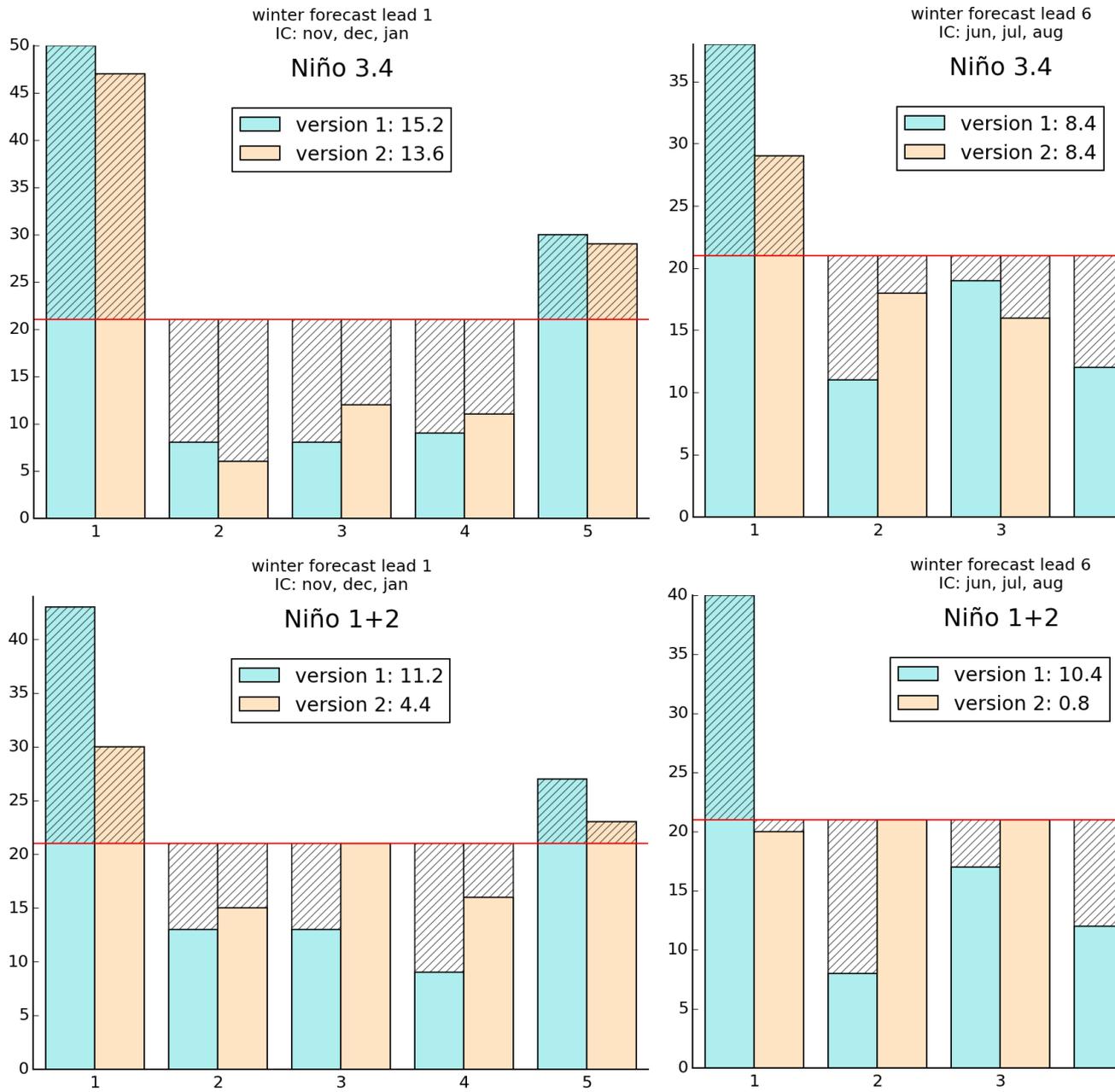


728 **Figure 25.** Anomaly correlation for Niño 3.4 SST index. Reynolds SST as observations. First forecast  
 729 month is on the y-axis, lead time on the x-axis. Left panel S2S-1\_0, middle S2S-2\_1, right S2S-1\_0 minus  
 730 S2S-2\_1.



**Figure 26.** Same as 25, but for Niño1+2 index.

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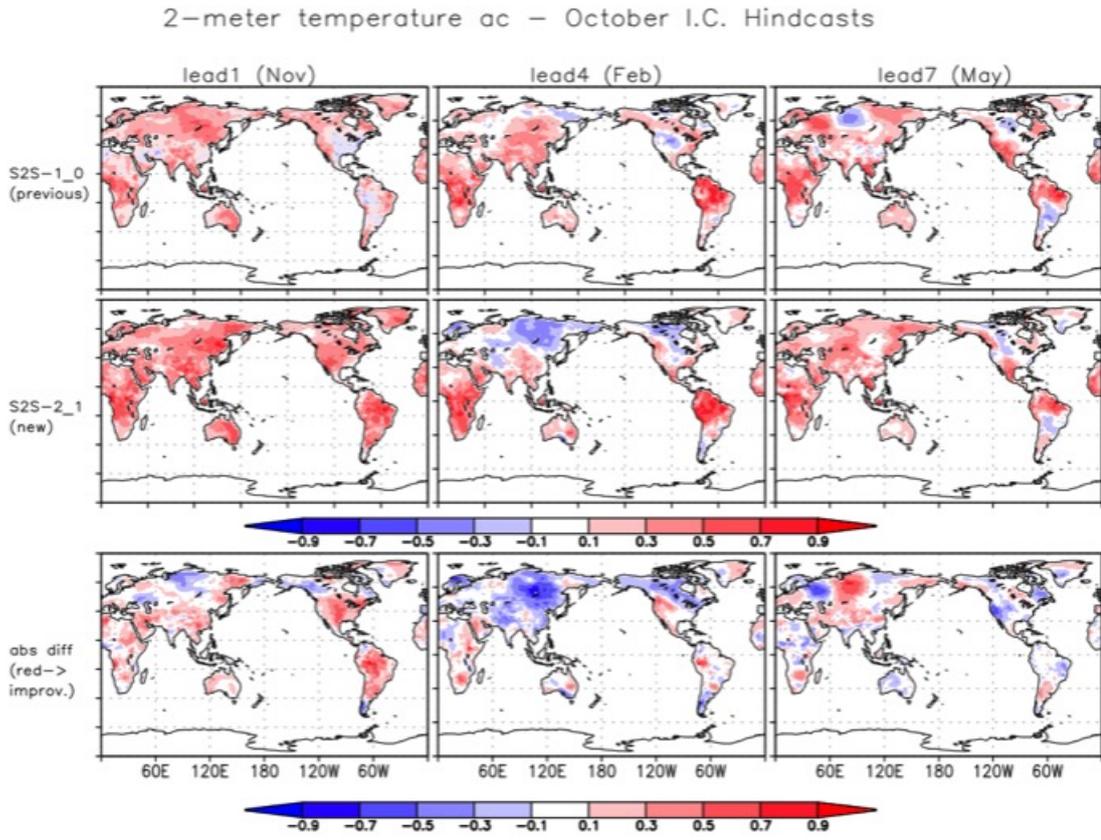


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**Figure 27.** Rank histogram for winter (DJF) forecasts at lead 1 (IC:NDJ) and lead 6 (IC:JJA). S2S\_1-0

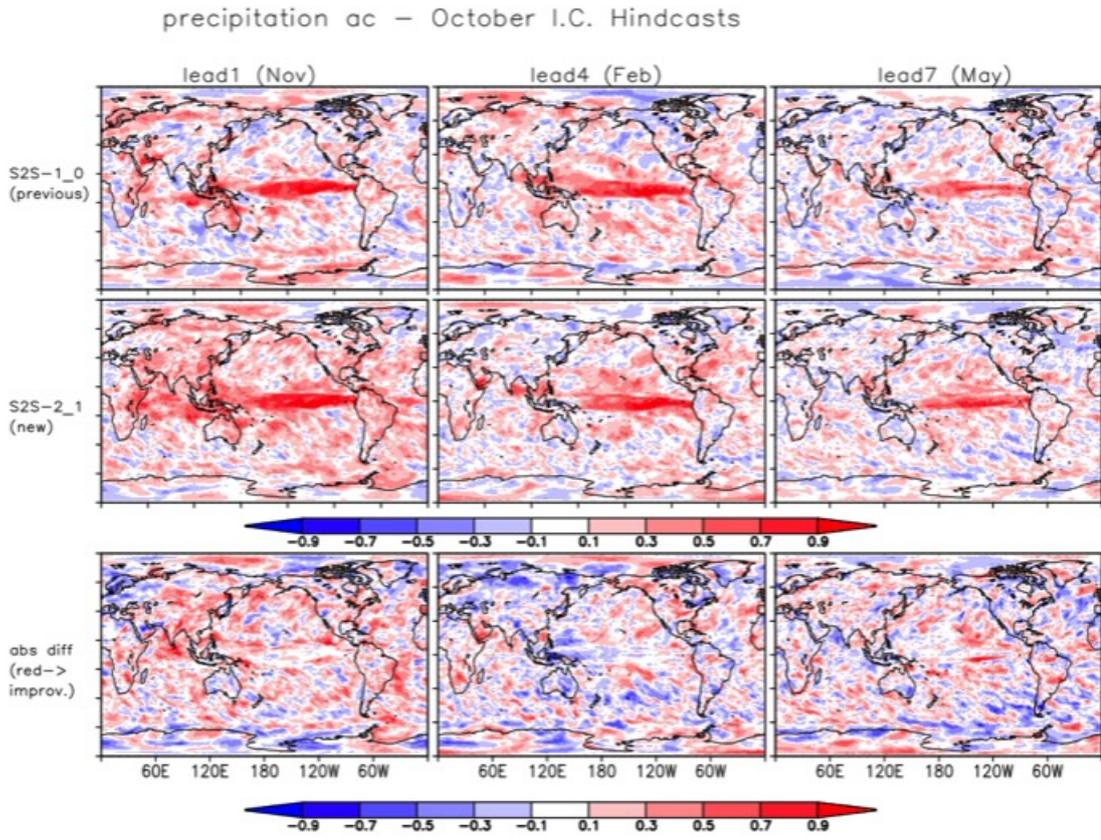
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shown in aqua, S2S\_2-1 in tan color.



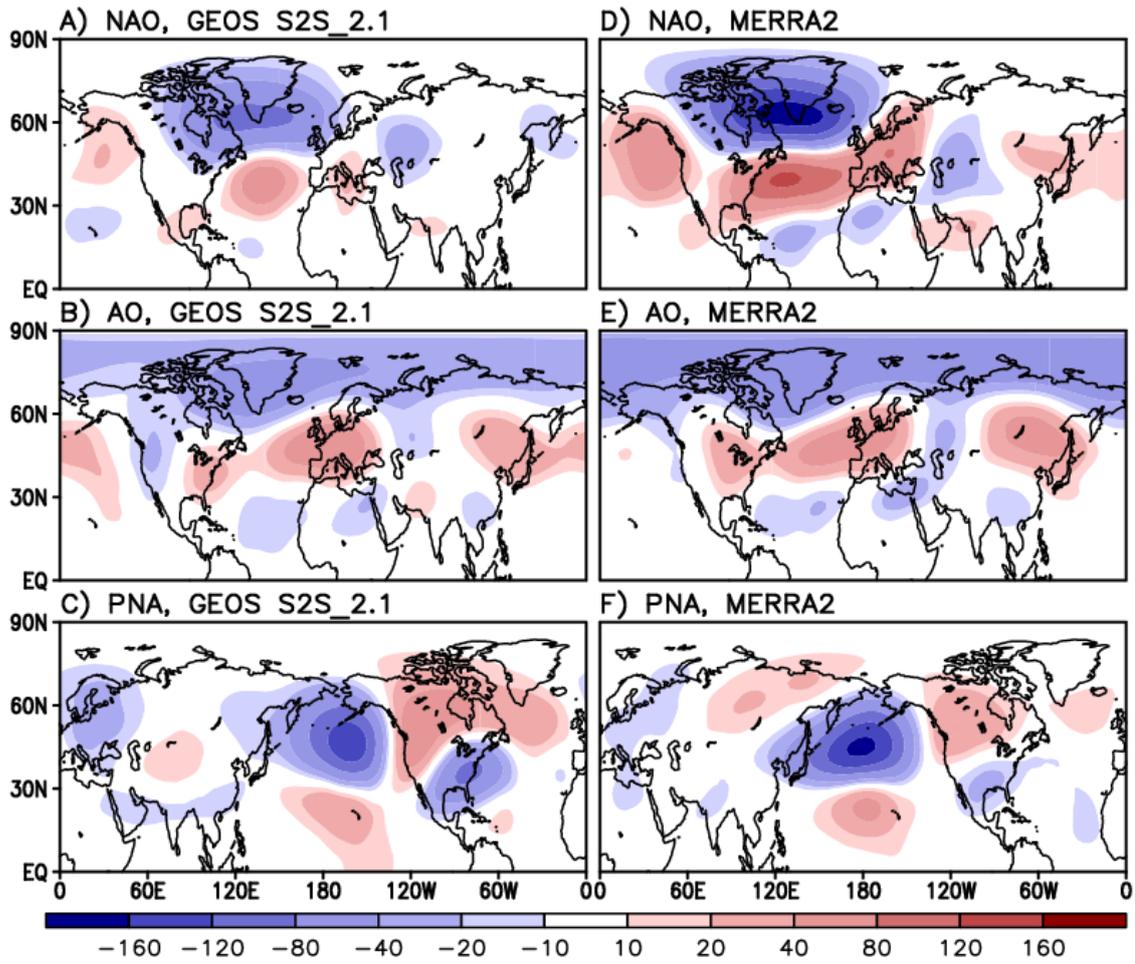
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**Figure 28.** T2m skill in reforecasts



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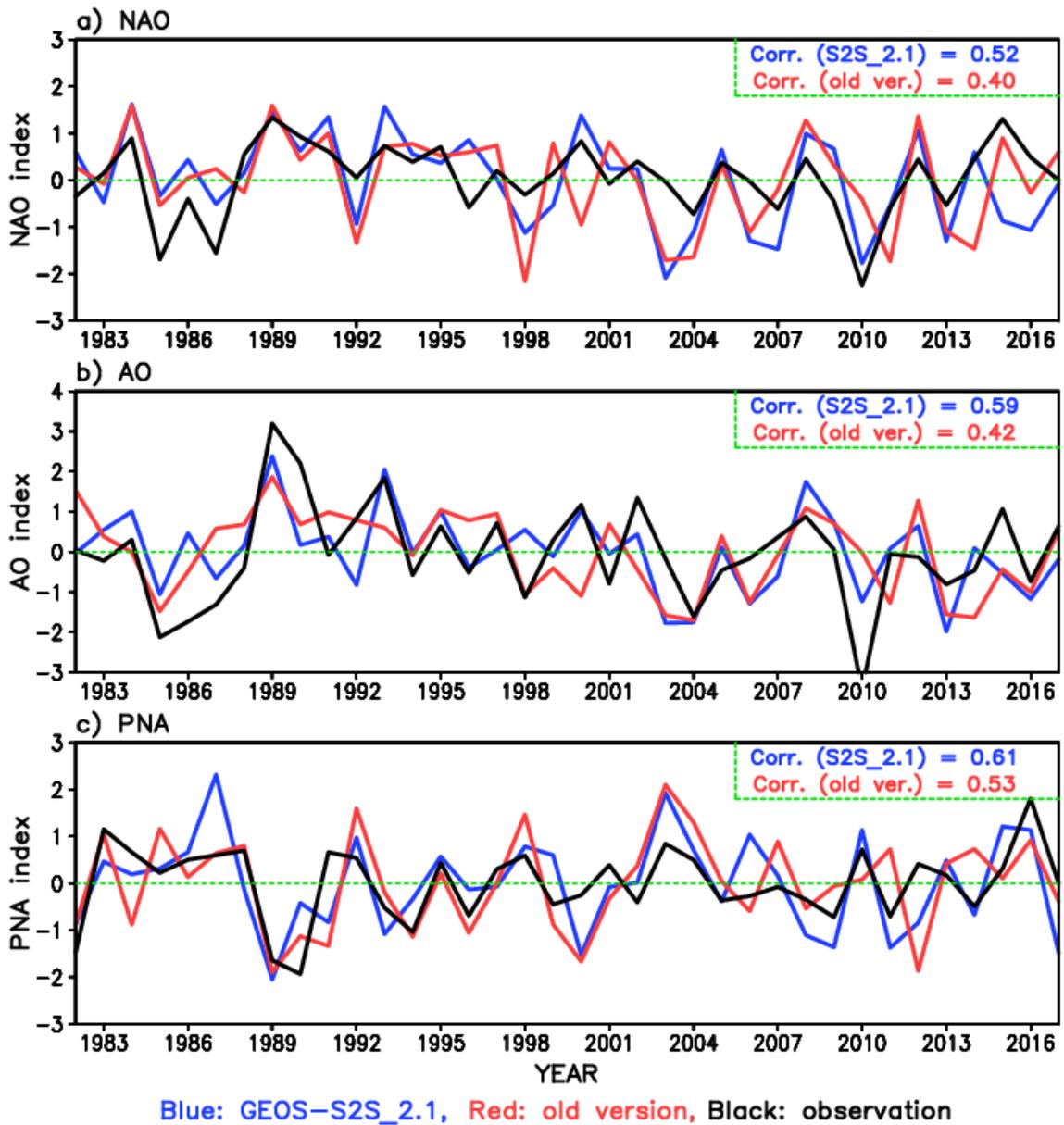
**Figure 29.** Prec skill in reforecasts



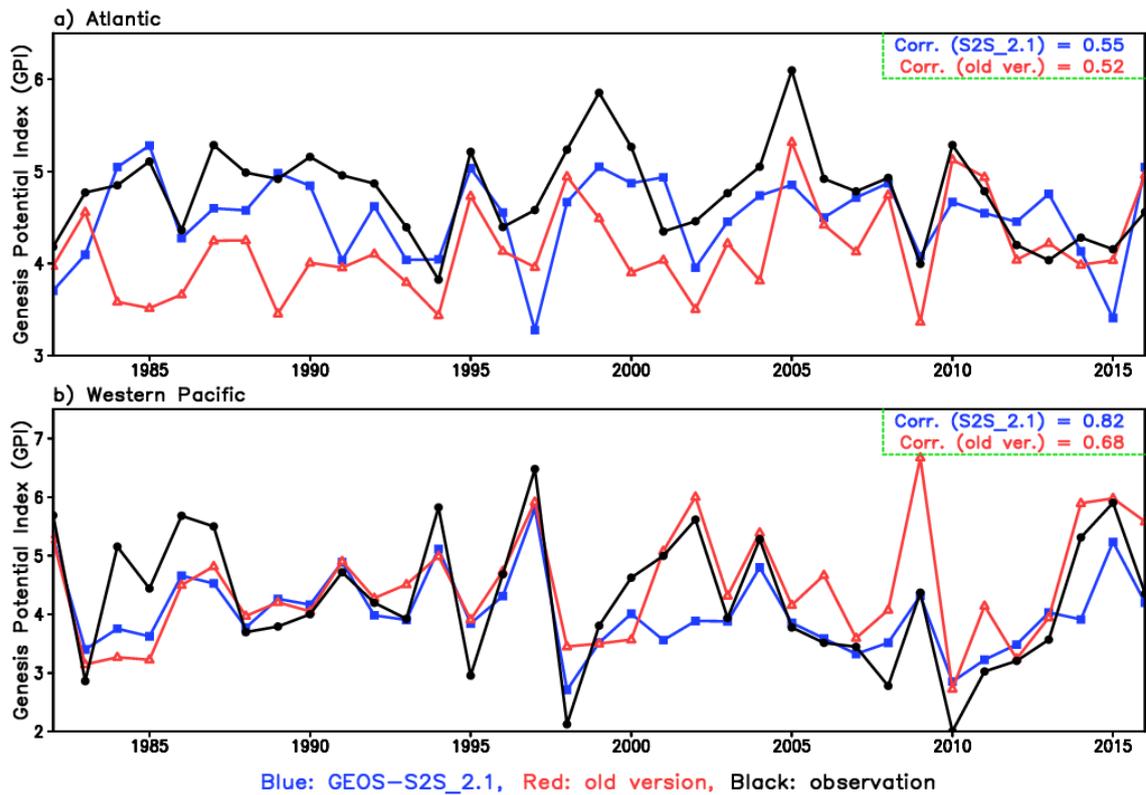
**Figure 30.** Major teleconnection patterns captured by GEOS S2S-2.1 and MERRA2

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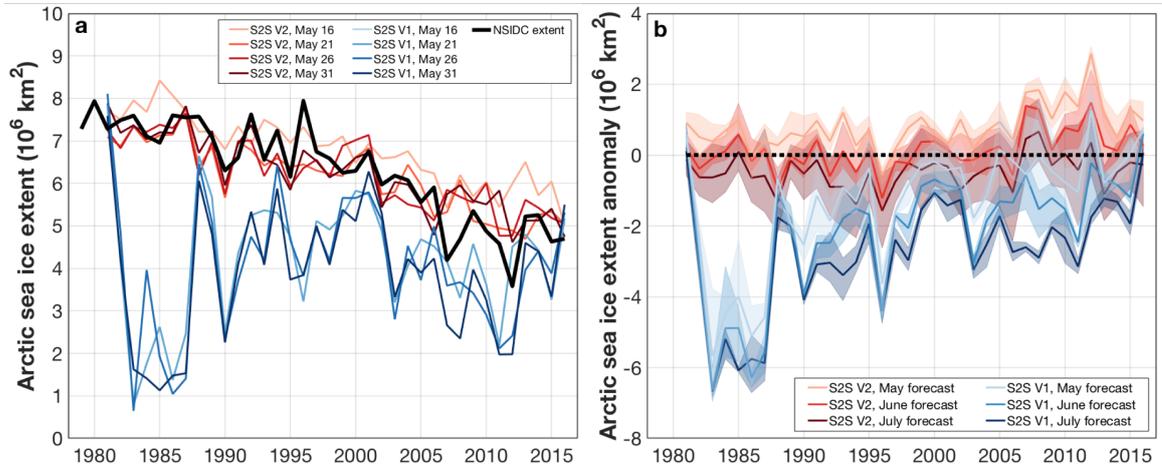




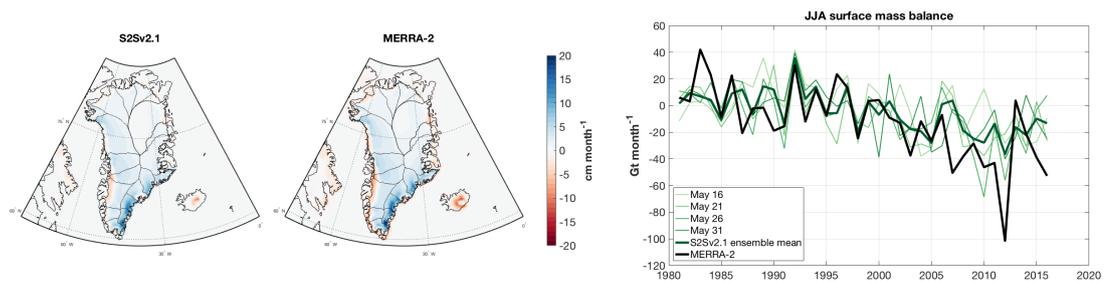
775 **Figure 31.** January/February mean NAO (top), AO (middle), and PNA (bottom) teleconnection indices  
 776 predicted by GEOS S2S\_2.1 (blue) and old model version (red) initialized on 27 December. Black line repre-  
 777 sents the observed teleconnection indices. Correlations between observation and GEOS S2S\_2.1 (blue), and  
 778 between observation and old model version (red), are, respectively, given on the upper-right corner of the each  
 779 panel.



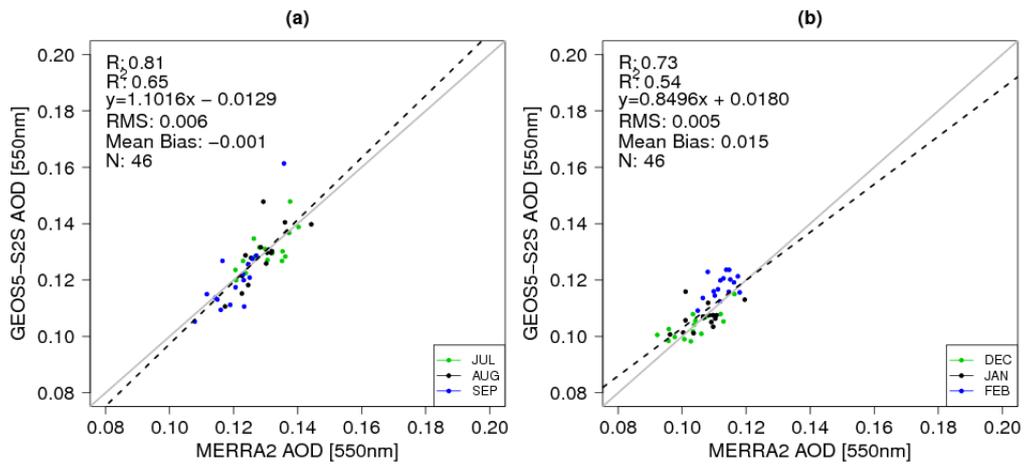
792 **Figure 32.** Predicted tropical cyclone activity in terms of the genesis potential index (GPI) initialized on 31  
 793 May. The predicted GPIs averaged over June/July/August/September (JJAS) each year are examined for the  
 794 North Atlantic (upper) and the Western Pacific (bottom) region, respectively. Blue, red, and black solid lines  
 795 denote the results from the S2S\_2.1, old model version, and MERRA-2. Correlations between MERRA-2  
 796 and S2S\_2.1 (blue), and between MERRA-2 and old model version are, respectively, given on the upper-right  
 797 corner of the each panel.



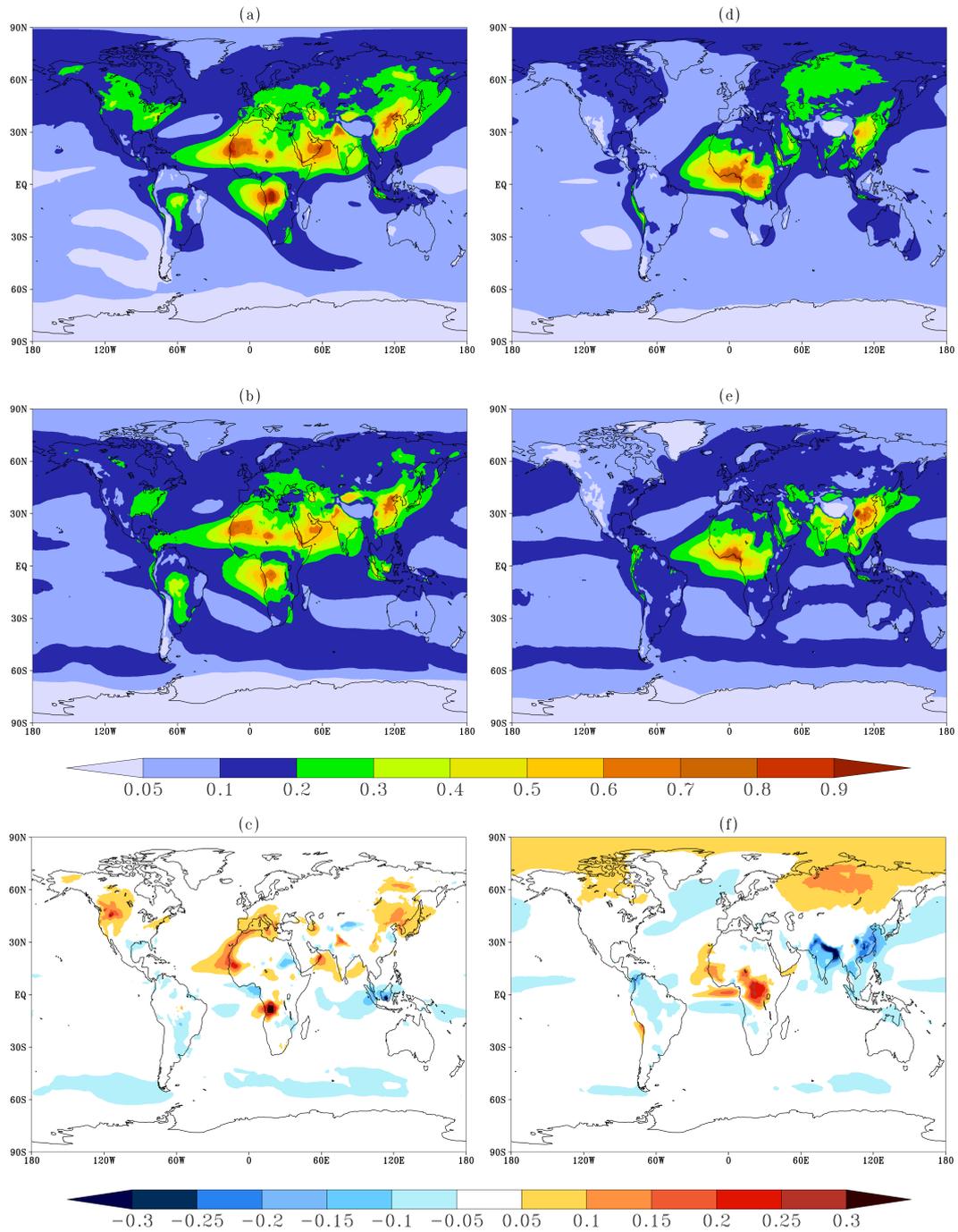
905 **Figure 33.** a. June retrospective forecast ensemble variability of September Northern Hemisphere sea ice  
 906 extent for GEOS S2S Version 1 (blues) and Version 2 (reds) compared to sea ice concentrations derived from  
 907 satellite brightness temperature (black, *Cavalieri et al.* [1996]). b. May, June, and July retrospective forecast  
 908 anomalies of GEOS S2S Version 1 and Version 2 (as differenced from *Cavalieri et al.* [1996]) for September  
 909 Northern Hemisphere sea ice extent. The ensemble spread for each forecast is indicated with the shaded bars.



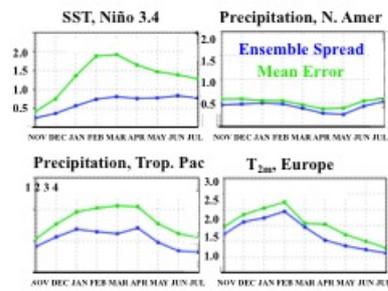
910 **Figure 34.** a. S2Sv2.1 mean one month lead ice sheet surface mass balance over the retrospective forecast  
 911 period (1981-2016) b. Mean ice sheet surface mass balance (1981-2016) c. Greenland ice sheet summer (JJA)  
 912 surface mass balance predicted from forecasts initialized in May (thin green lines), the ensemble mean (thick  
 913 green line) and MERRA-2 (thick black line).



968 **Figure 35.** Monthly mean AOD globally averaged from GEOS5-S2S ensemble mean compared to  
 969 MERRA2 for the period 2000- 2015 for (a) July-August-September, and (b) December-January-February.  
 970 The colors indicate the months, the solid gray the 1-1 line, and the dashed regression linear line. Statistics are  
 971 computed in natural log-transformed AOD space.



972 **Figure 36.** Spatial distribution of aerosol optical depth at 550nm in July-August-September (on the left)  
 973 and December-January-February (on the right) averaged for the period 2000-2015 from GEOS5-S2S ensemble  
 974 mean (top), reanalysis from MERRA2 (middle), and the GEOS5-S2S mean bias relative to MERRA2 (on  
 975 the bottom).



976

Figure 37.